

Overview and working principle of OSIRIS-T

Francesco Versaci

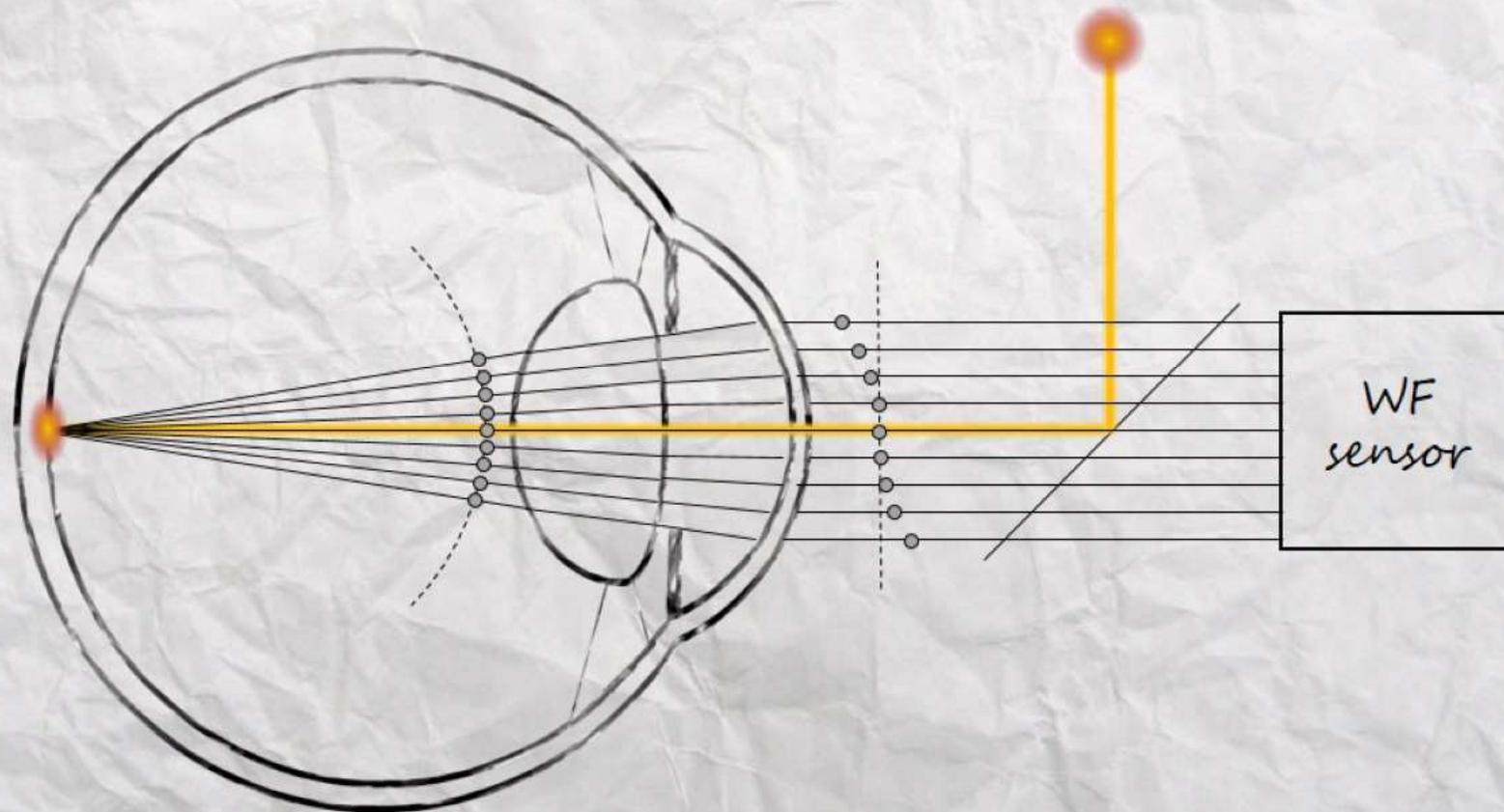
1° CSO distributor meeting

2018 - Venezia

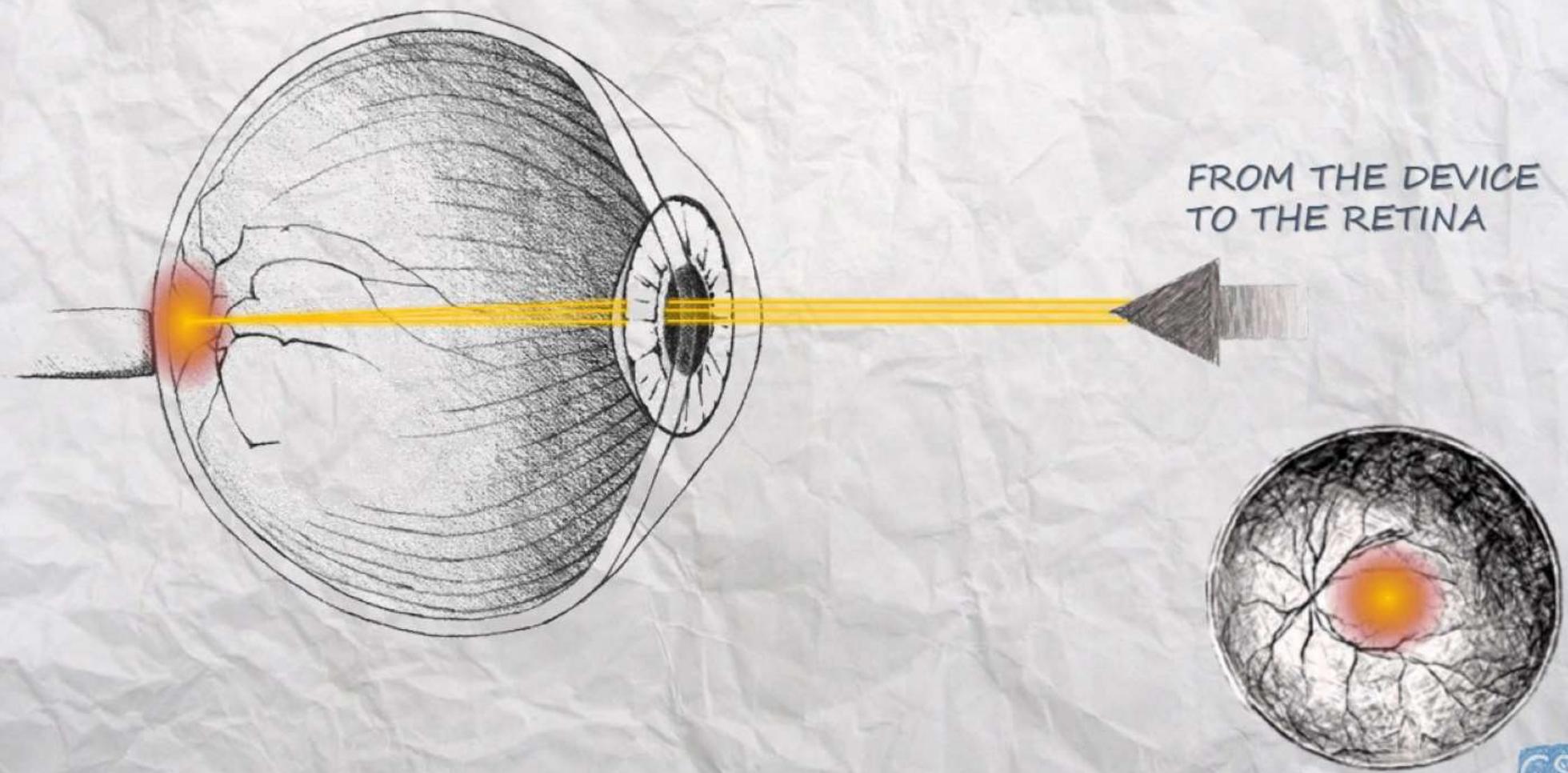


Working principle

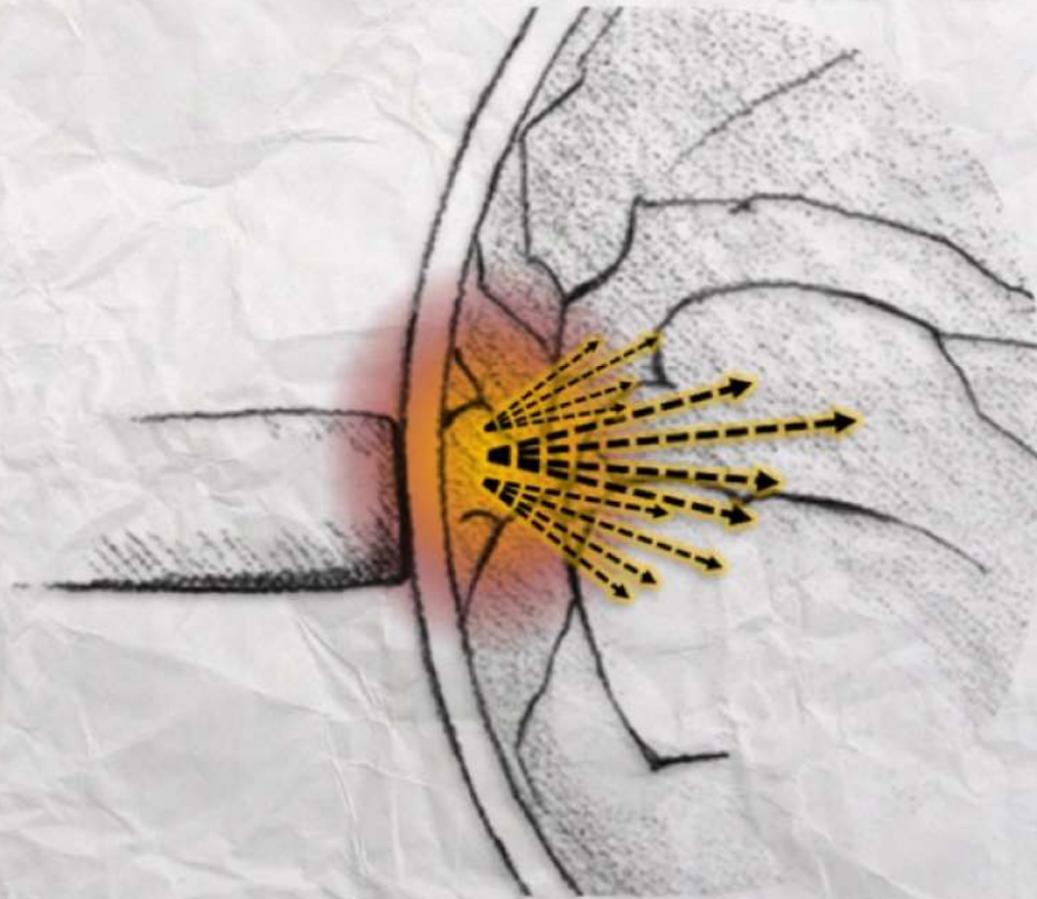
BASIC SCHEME OF AN ABERROMETER



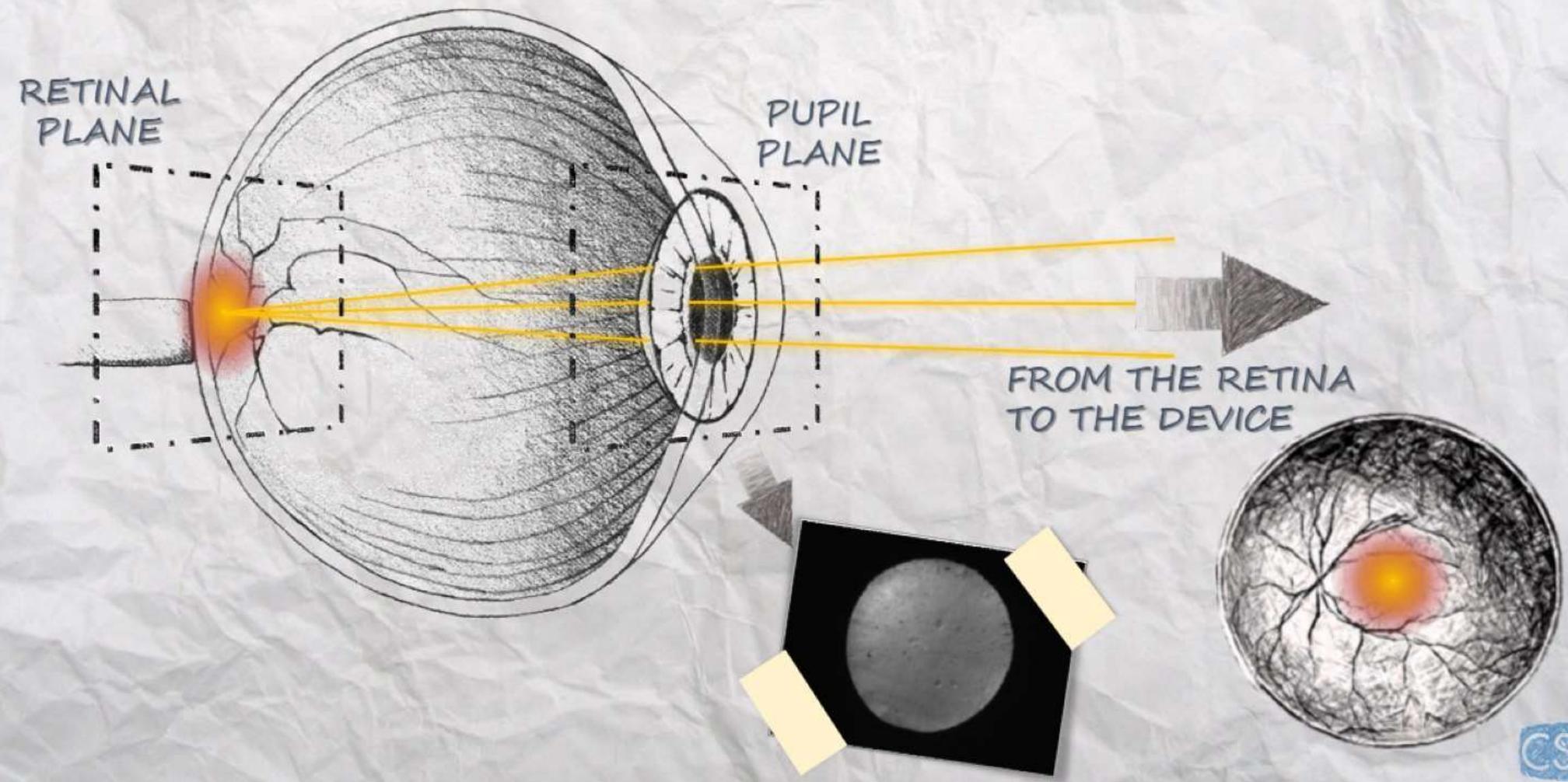
LIGHTING SYSTEM



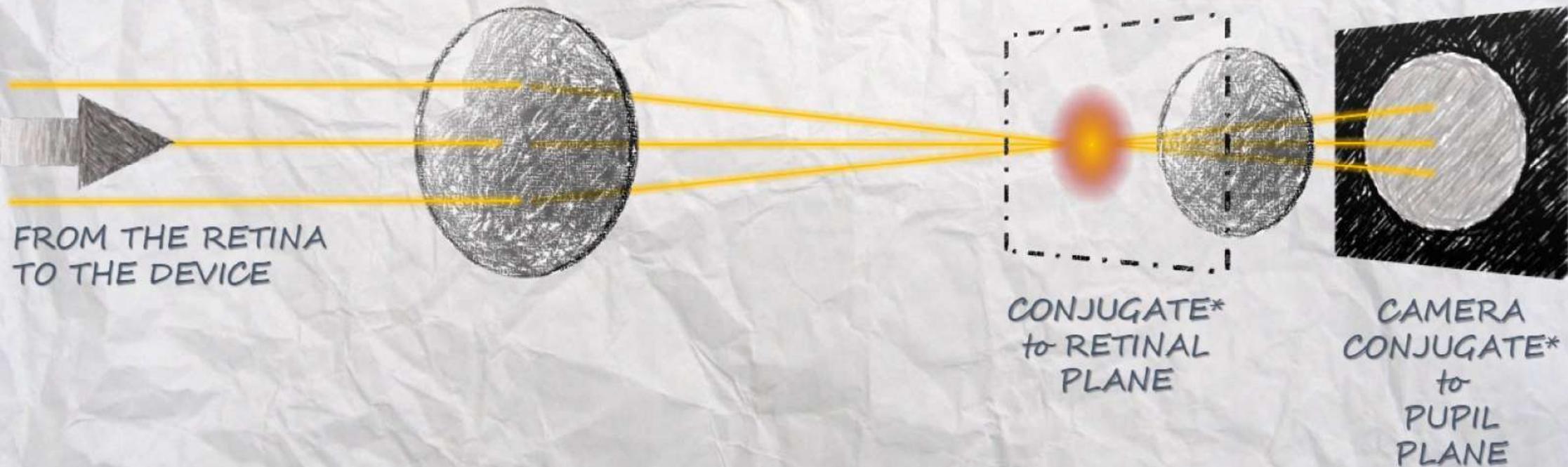
SCATTERING BACK TO THE DEVICE



REFLECTION BACK TO THE DEVICE

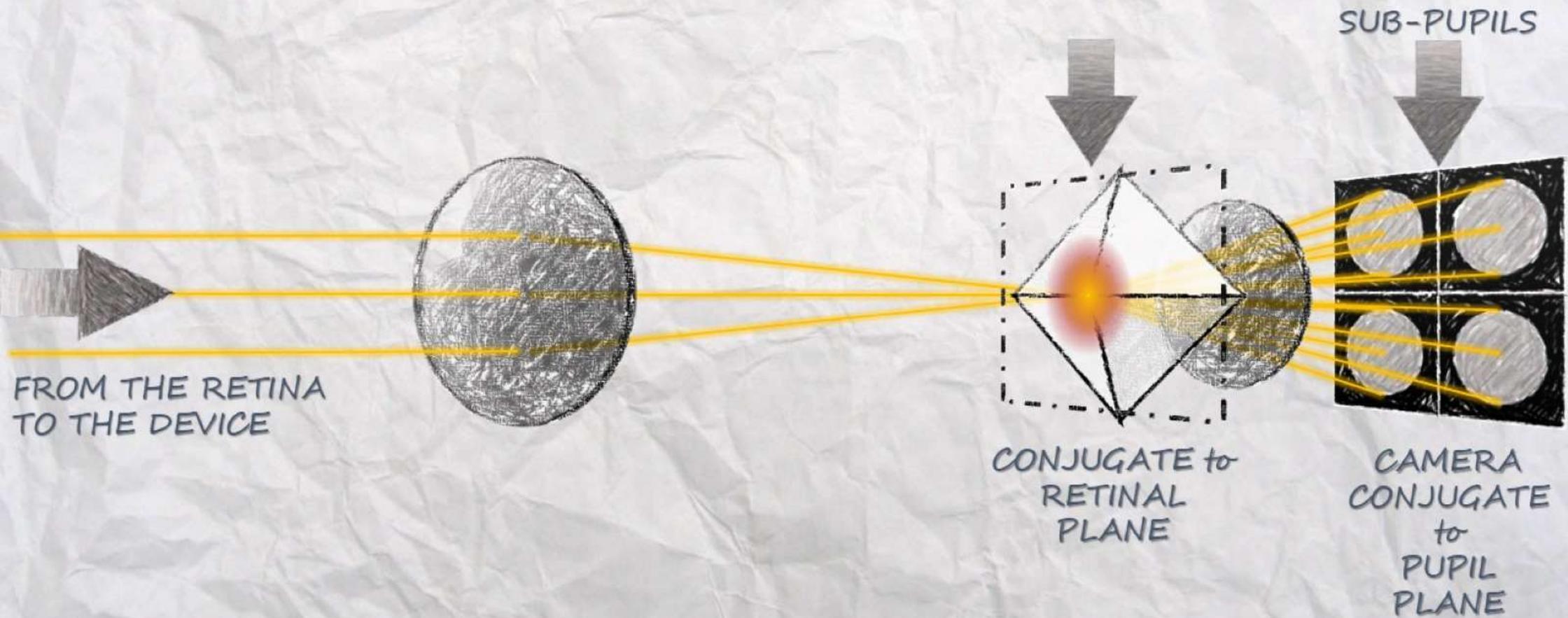


INTO OSIRIS-T...



IN OPTICS, A CONJUGATE FOCAL PLANE OF A GIVEN PLANE P , IS THE PLANE P^ SUCH THAT POINTS ON P ARE IMAGED ON P^* .

INTO OSIRIS-T...

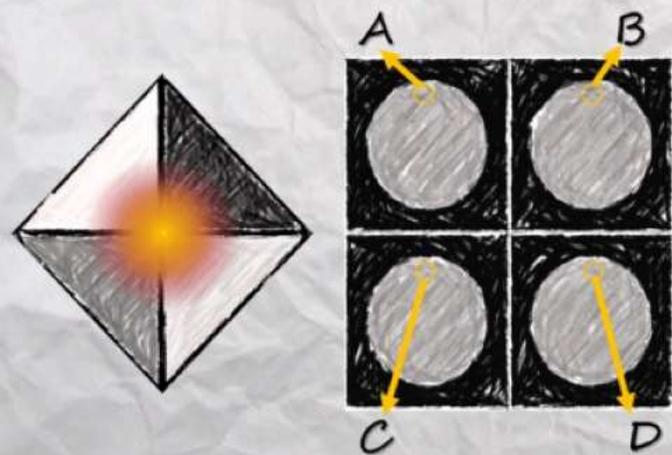
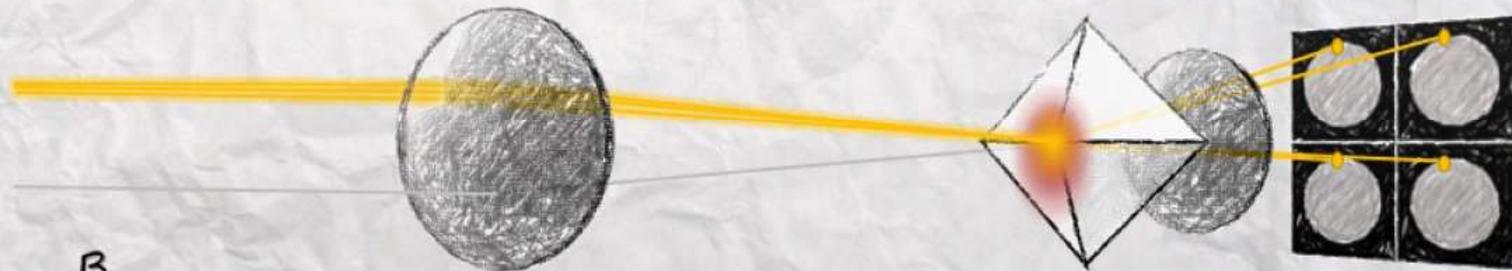
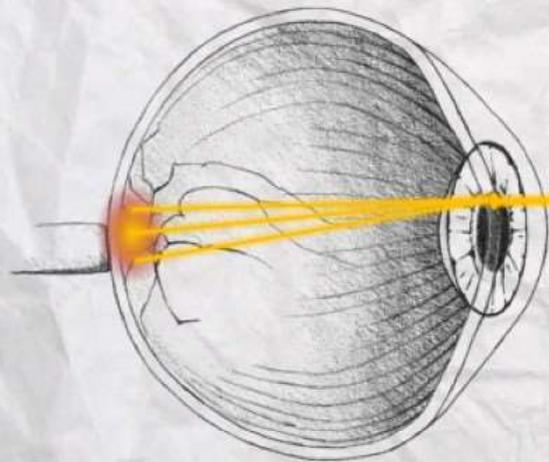


FROM THE RETINA
TO THE DEVICE

CONJUGATE to
RETINAL
PLANE

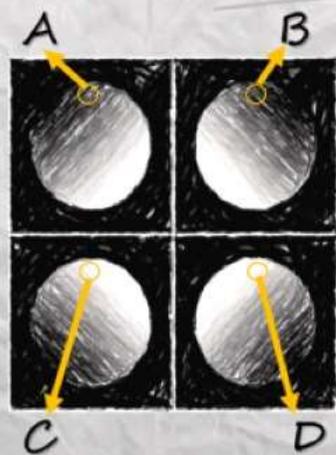
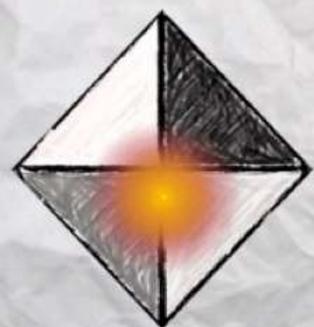
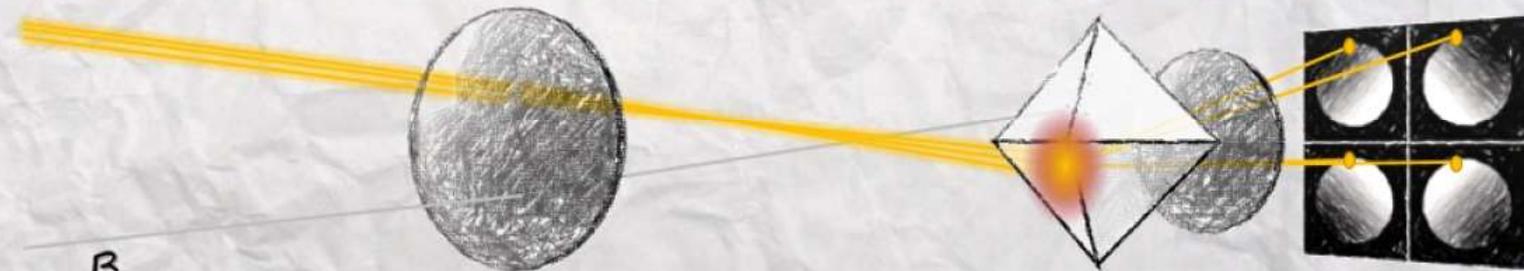
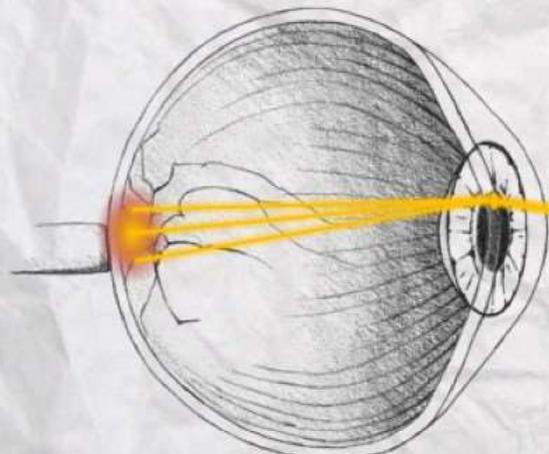
CAMERA
CONJUGATE
to
PUPIL
PLANE

EMMETROPIC RAY (SLOPE = 0): Y-AXIS



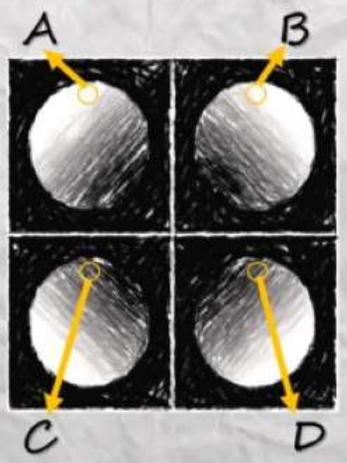
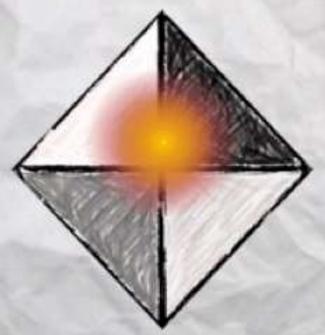
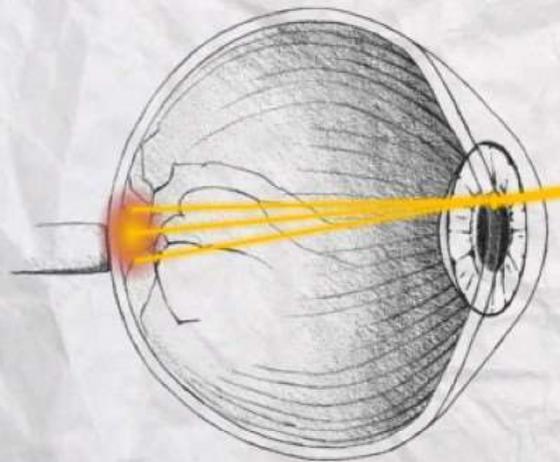
$$A = B = C = D$$

CONVERGENT RAY (SLOPE < 0): Y-AXIS



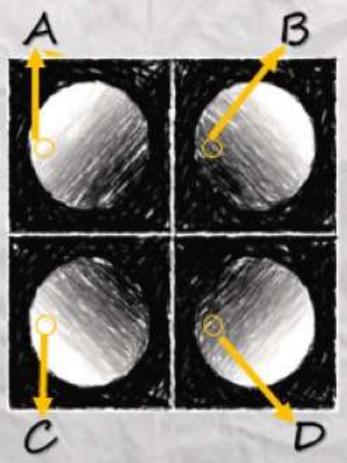
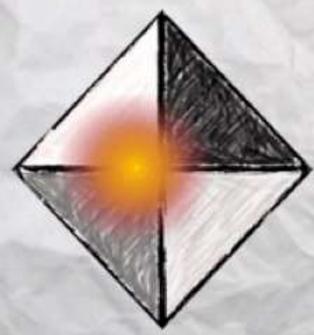
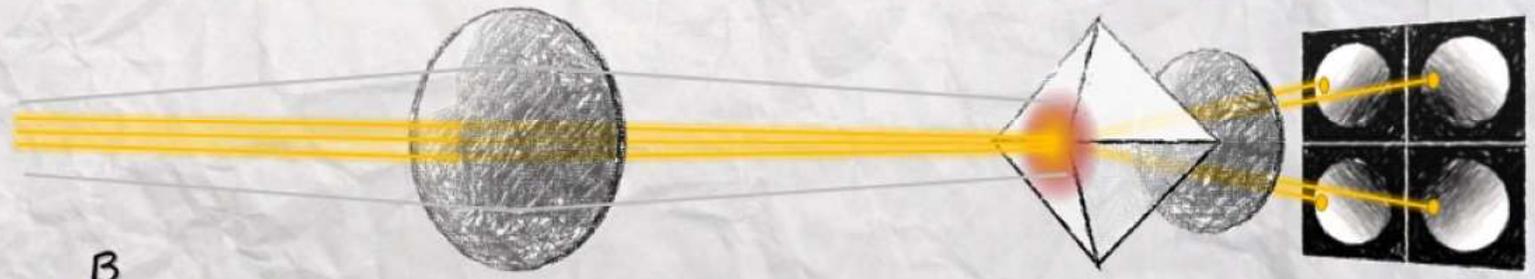
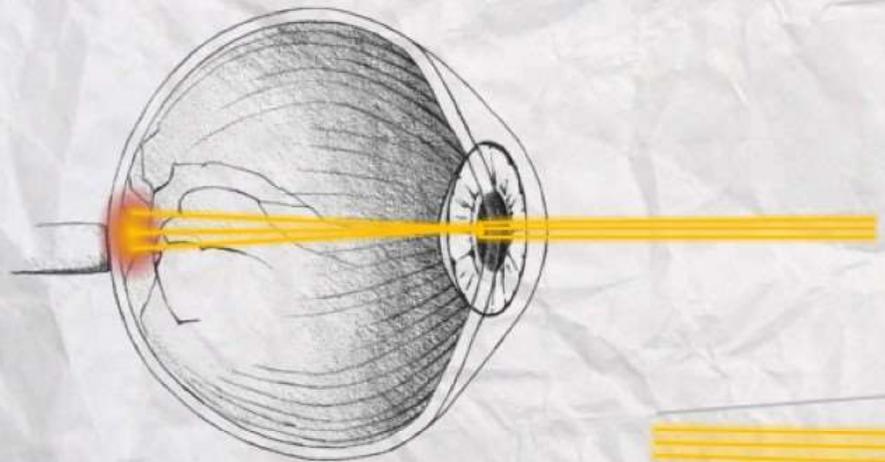
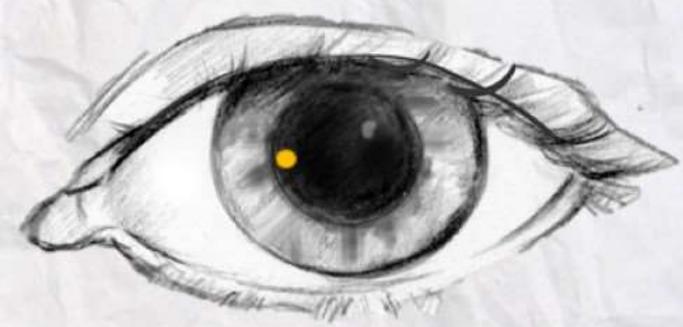
$$A < C$$
$$B < D$$
$$(A=B, C=D)$$

DIVERGENT RAY (SLOPE > 0): Y-AXIS



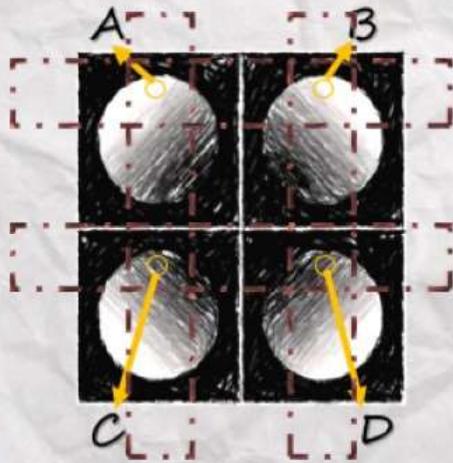
$$A > C$$
$$B > D$$
$$(A=B, C=D)$$

DIVERGENT RAY (SLOPE > 0): X-AXIS



$$A > B$$
$$C > D$$
$$(A=C, B=D)$$

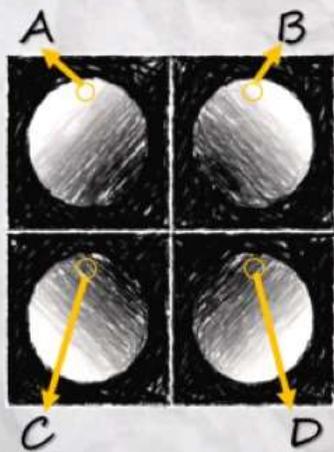
RELATIONSHIP SLOPE-LIGHT INTENSITY



$$\frac{\partial WF}{\partial y} \propto \frac{A+B-C-D}{A+B+C+D}$$

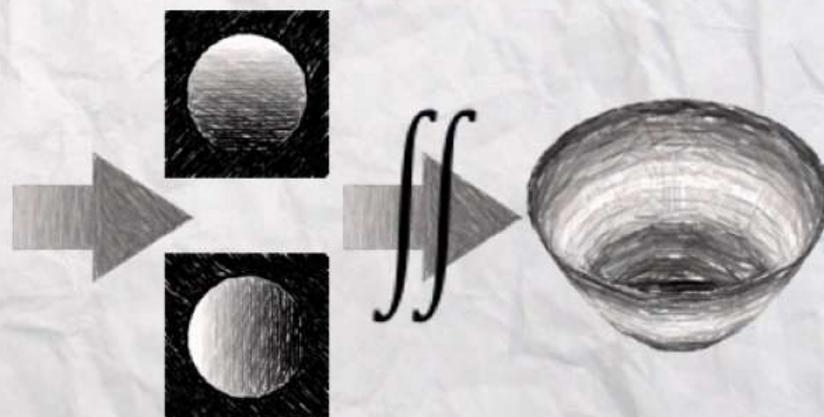
$$\frac{\partial WF}{\partial x} \propto \frac{A+C-B-D}{A+B+C+D}$$

WAVE-FRONT ERROR



$$\frac{\partial WF}{\partial y} \propto \frac{A+B-C-D}{A+B+C+D}$$

$$\frac{\partial WF}{\partial x} \propto \frac{A+C-B-D}{A+B+C+D}$$



REFRACTIVE ERROR (VERGENCE ERROR)

Ocular aberrations with wavefront vergence maps Nam, Thibos and Iskander

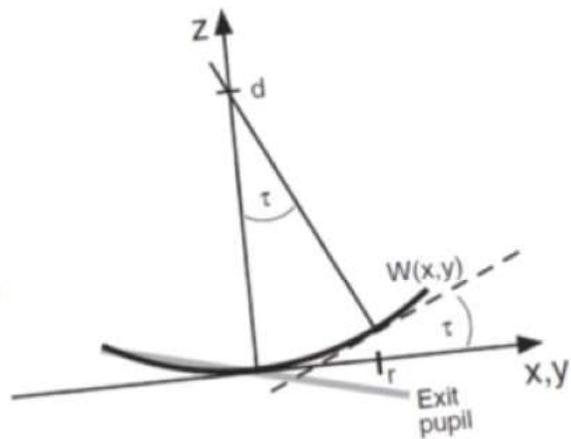
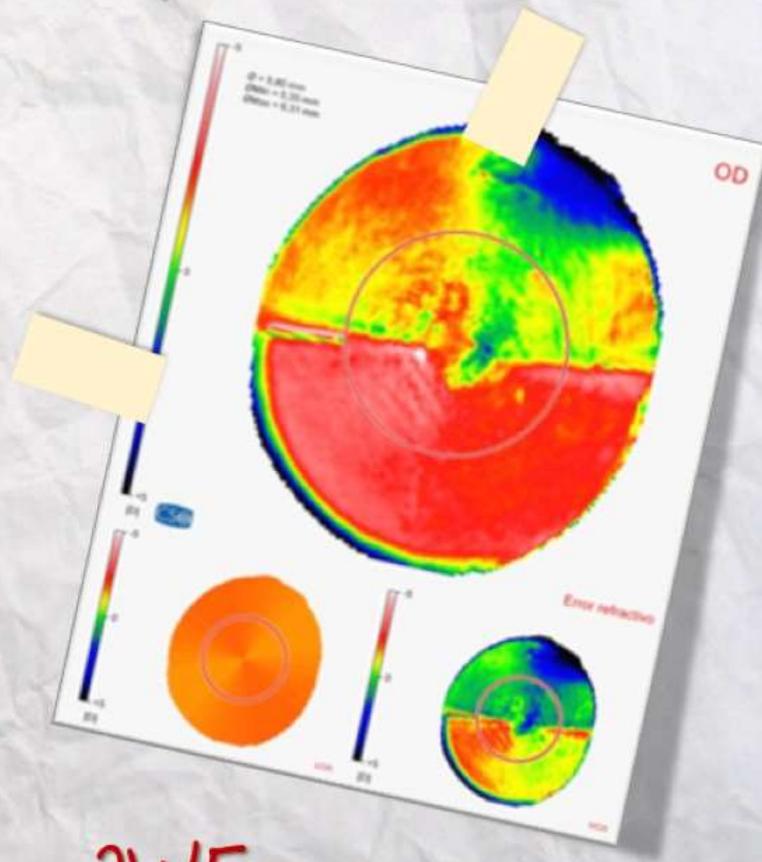


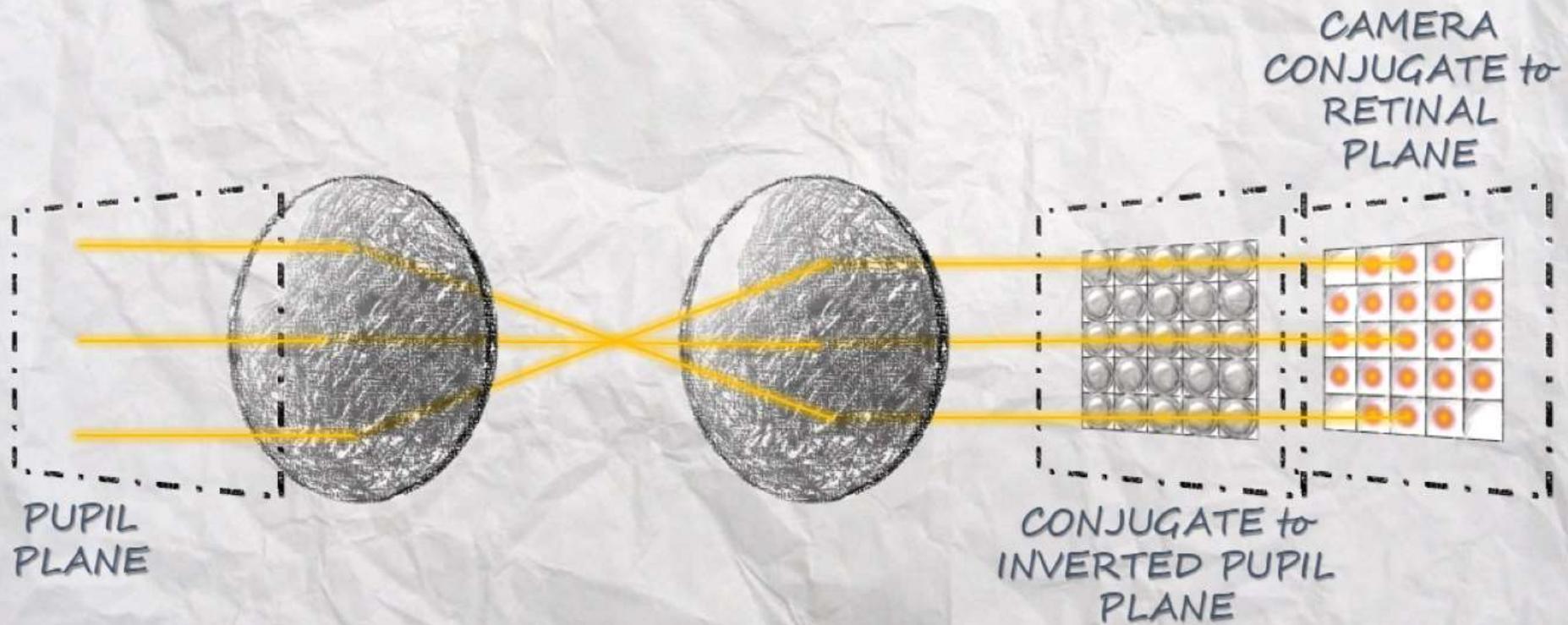
Figure 1. Geometry of the wavefront vergence definition. The z axis indicates the direction of the chief ray, which is not necessarily perpendicular to the exit pupil.



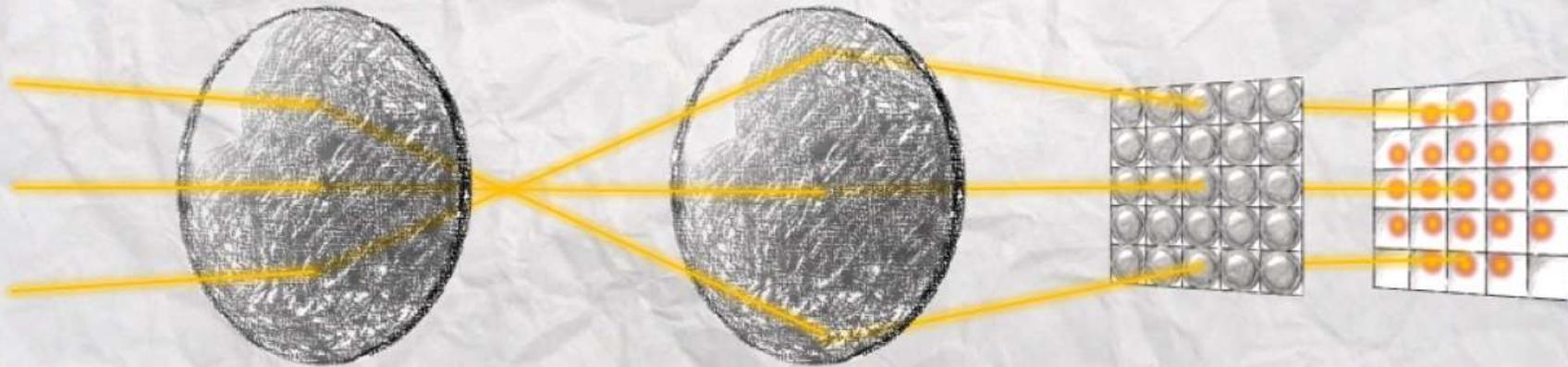
$$V(\rho, \theta) = \frac{1}{\rho} \frac{\partial W F}{\partial \rho} = \frac{1}{\rho} \left(\frac{\partial W F}{\partial x} \cos(\theta) + \frac{\partial W F}{\partial y} \sin(\theta) \right)$$

Comparison to
HARTMANN-SHACK

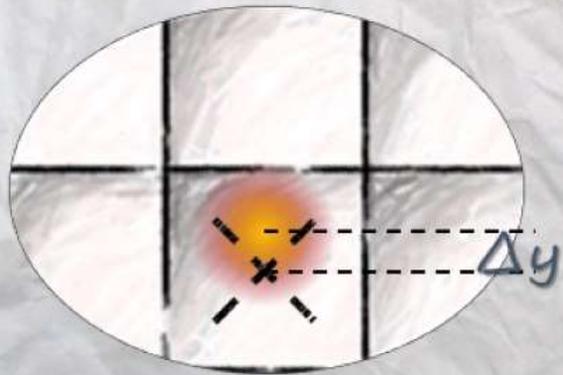
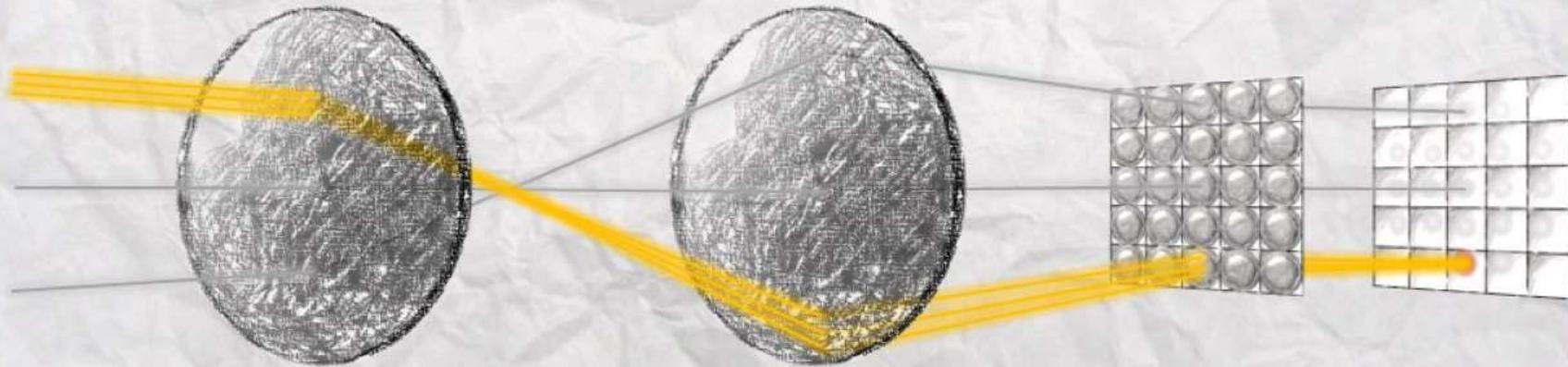
HARTMANN-SHACK



HARTMANN-SHACK: CONVERGENT WF



HARTMANN-SHACK: CONVERGENT RAY

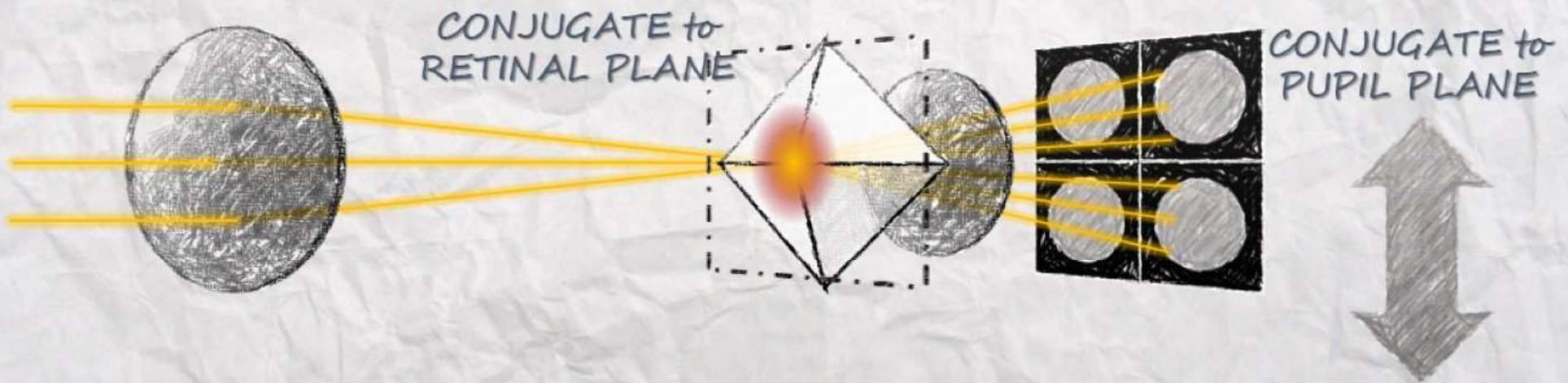


$$\frac{\partial WF}{\partial x} \propto \Delta x$$

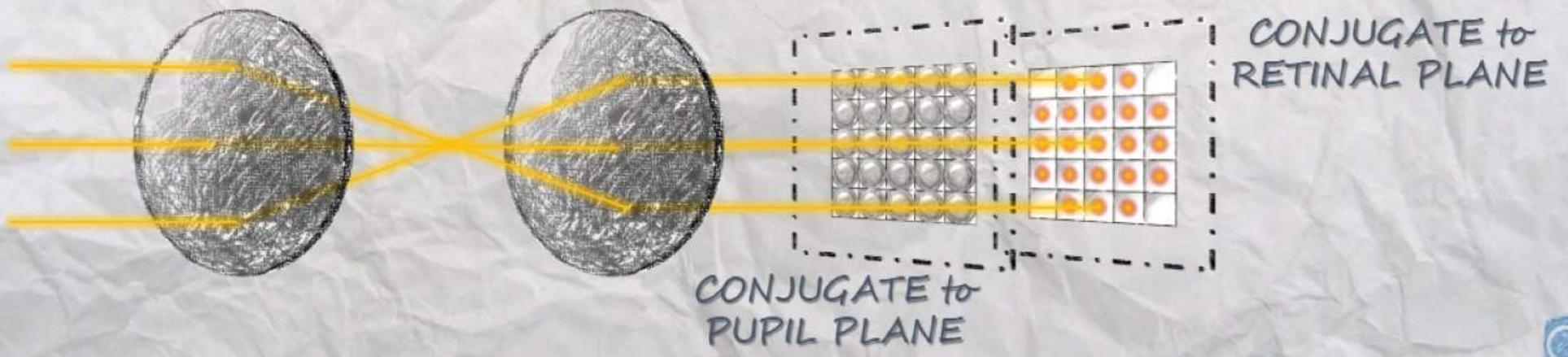
$$\frac{\partial WF}{\partial y} \propto \Delta y$$

COMPARISON: OPTICAL SETUP

PWS

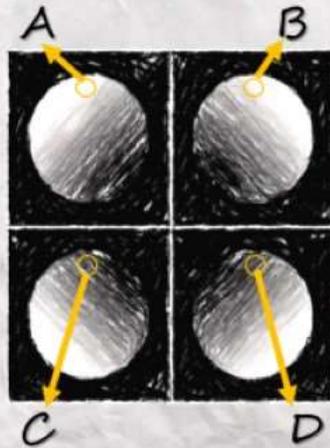


HS



COMPARISON: WORKING PRINCIPLE

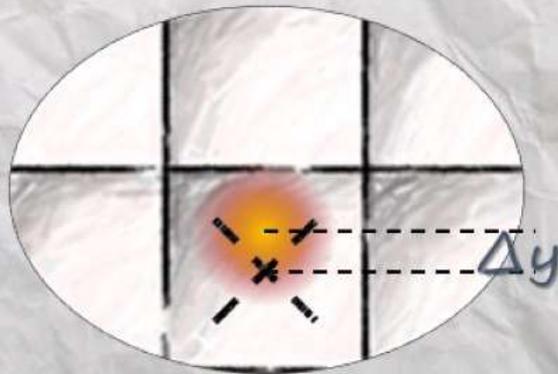
PWS



$$\frac{\partial WF}{\partial x} \propto \frac{A+C-B-D}{A+B+C+D}$$

$$\frac{\partial WF}{\partial y} \propto \frac{A+B-C-D}{A+B+C+D}$$

HS



$$\frac{\partial WF}{\partial x} \propto \Delta x$$

$$\frac{\partial WF}{\partial y} \propto \Delta y$$

COMPARISON: RESOLUTION

PWS

$N = \#$ POINTS ON A SUB-PUPIL

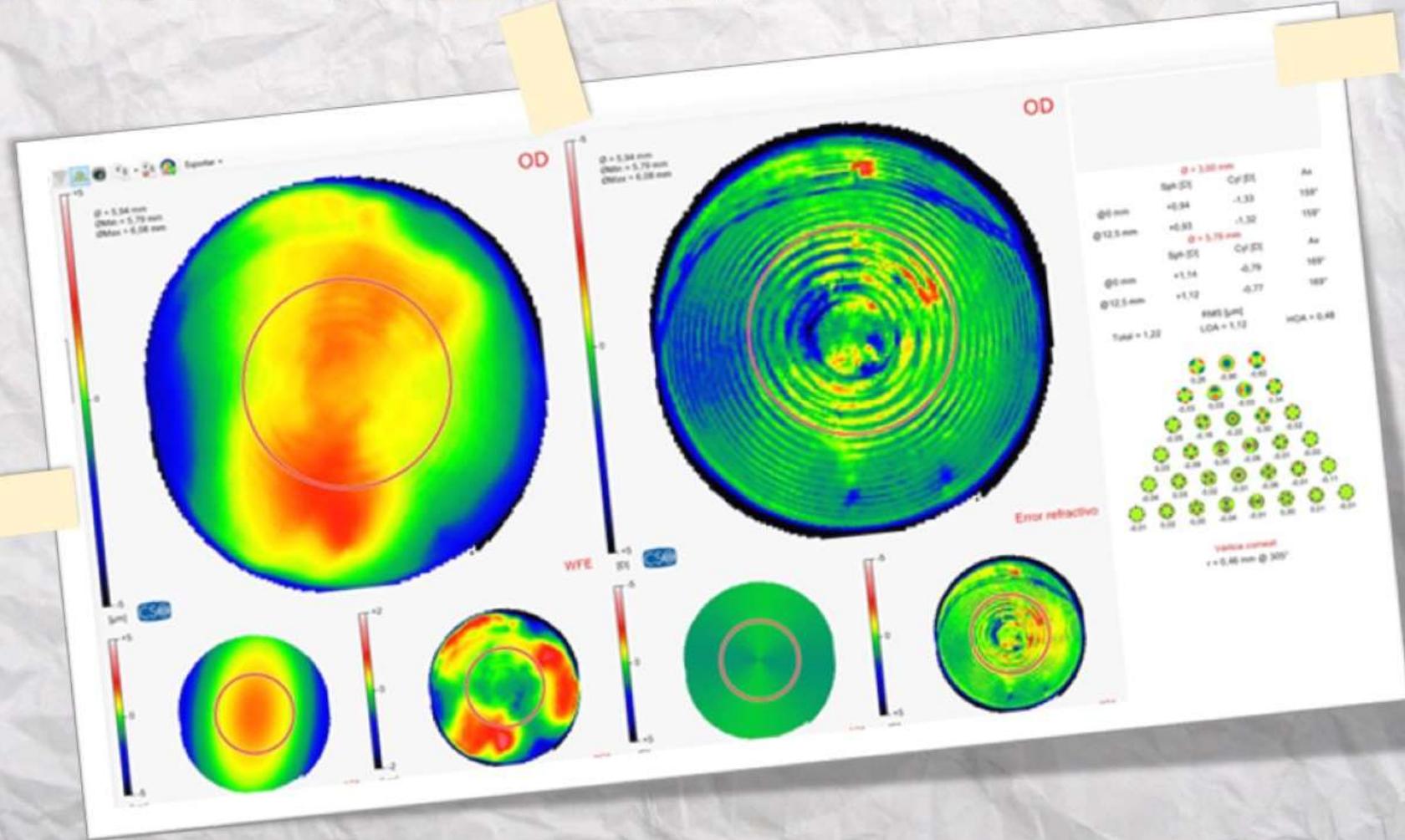
- 45.000 SAMPLES ($\phi = 9.0$ mm)
- SPATIAL RESOLUTION: 41 μm

HS

$N = \#$ LENSES ON THE LENSLET

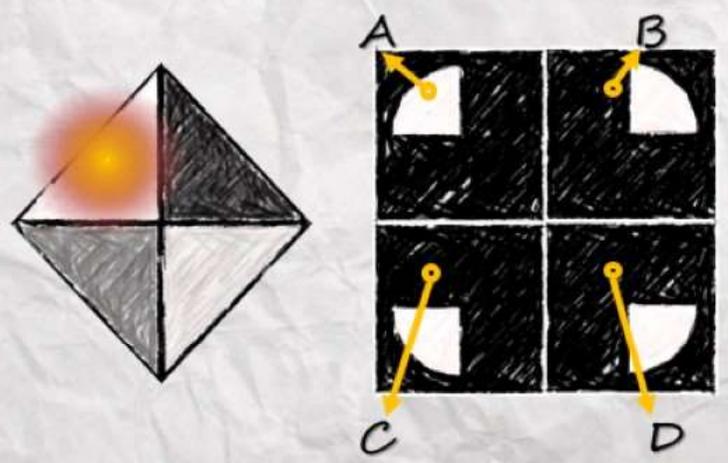
- 1.000-2.000 SAMPLES ($\phi = 9.0$ mm)
- SPATIAL RESOLUTION: 250-125 μm

COMPARISON: RESOLUTION



COMPARISON: SATURATION & DYNAMIC RANGE

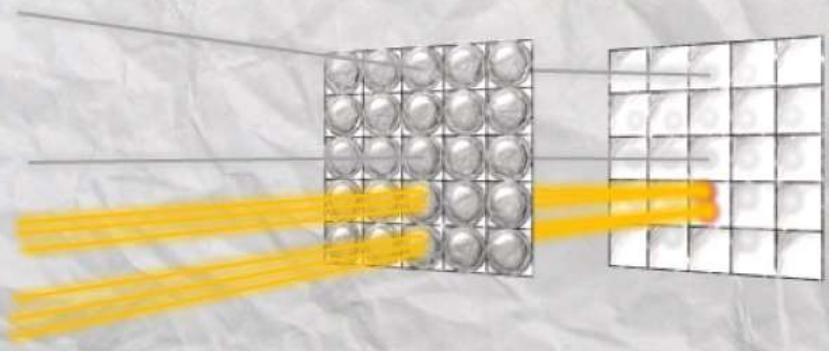
PWS



$$\frac{\partial WF}{\partial y} \propto \frac{A+B-C-D}{A+B+C+D} = 1$$

$B=C=D=0$
↓

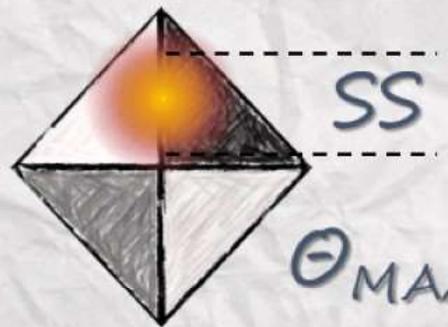
HS



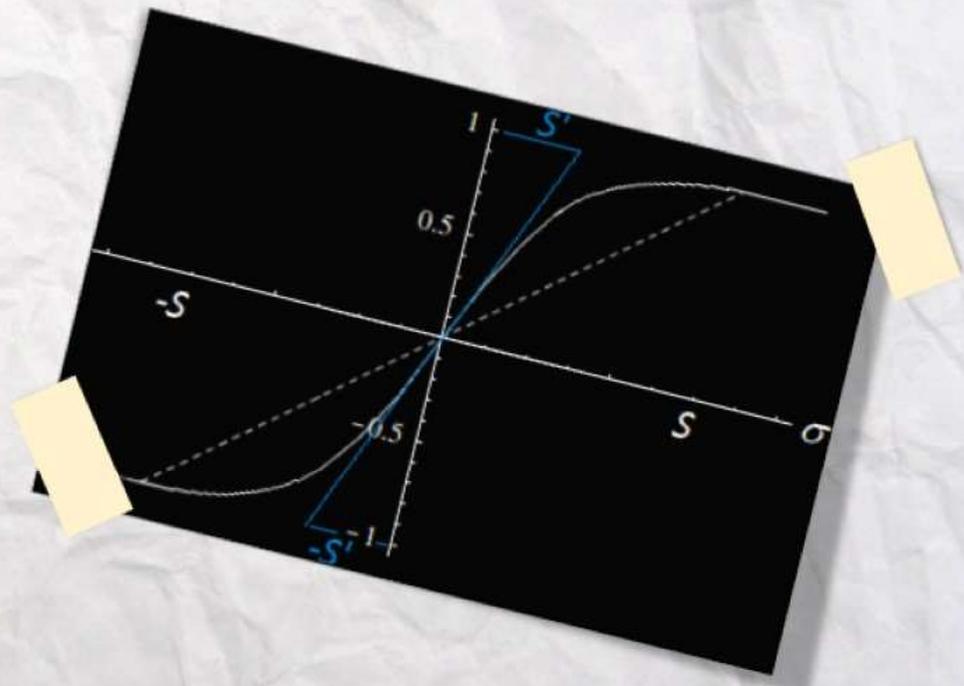
$$\frac{\partial WF}{\partial y} \propto \Delta y = ?$$

COMPARISON: SATURATION & DYNAMIC RANGE

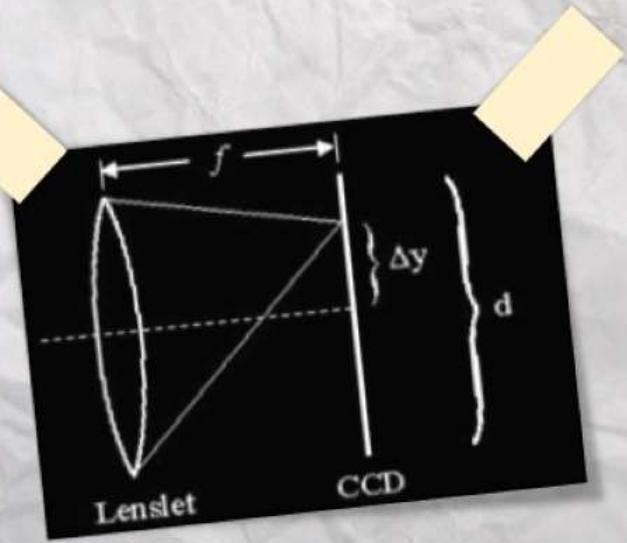
PWS



$$\theta_{MAX} \propto SS$$



HS



$$\theta_{MAX} \propto \Delta y / f = d / 2f$$

COMPARISON: PROCESSING

PWS

DIRECT INTEGRATION METHOD

- 30 Fps (REAL TIME WF IMAGING)
- FITTING «OPTIONAL»

HS

MODAL (ZERNIKE FITTING)

- WF IMAGING «OFF LINE»
- FITTING MANDATORY

PROCESSING (REAL TIME ACCOMMODATION MEASUREMENT)

