

Overview and working principle of OSIRIS-T

Francesco Versaci

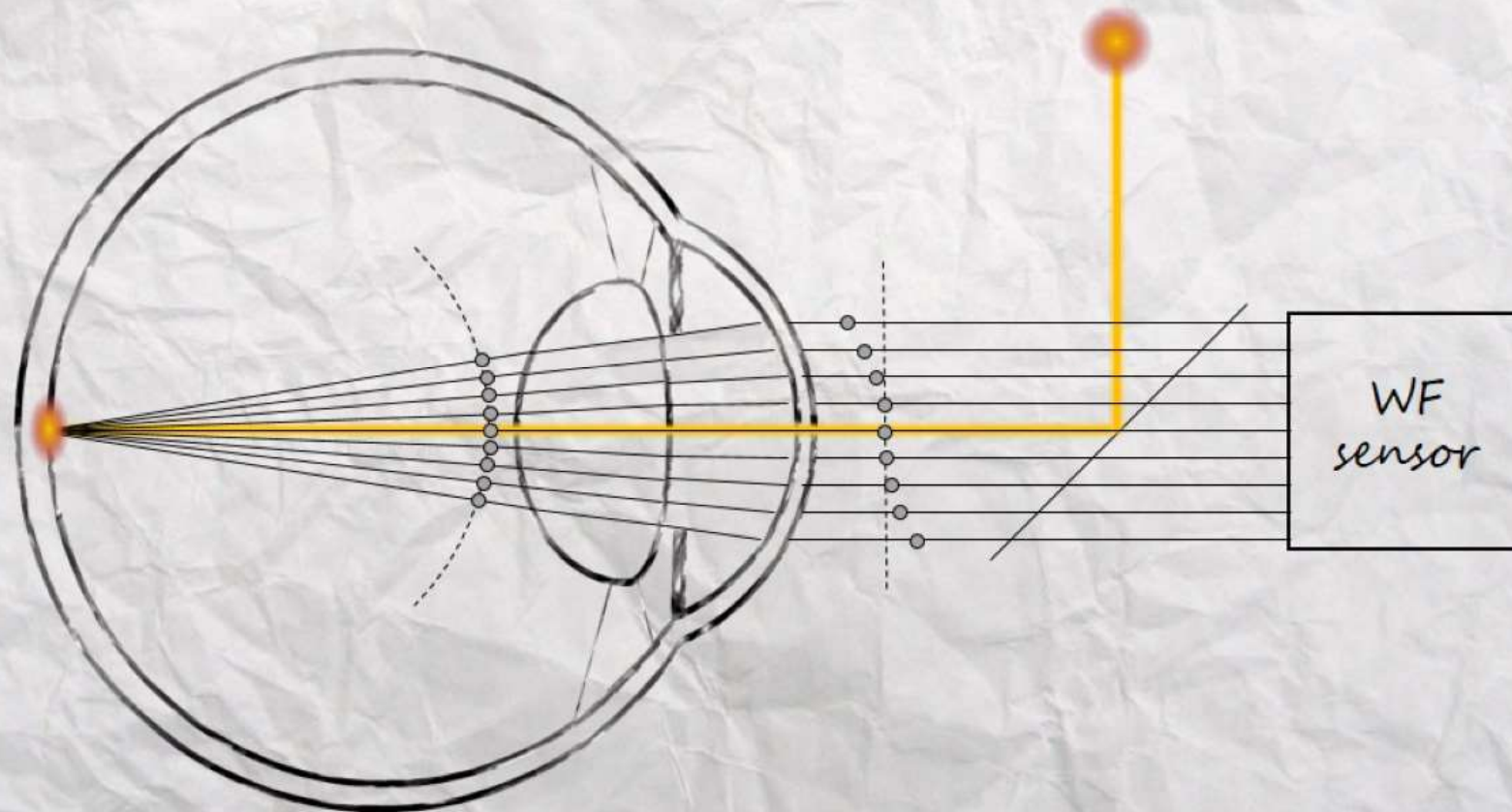
1° CSO distributor meeting

2018 - Venezia

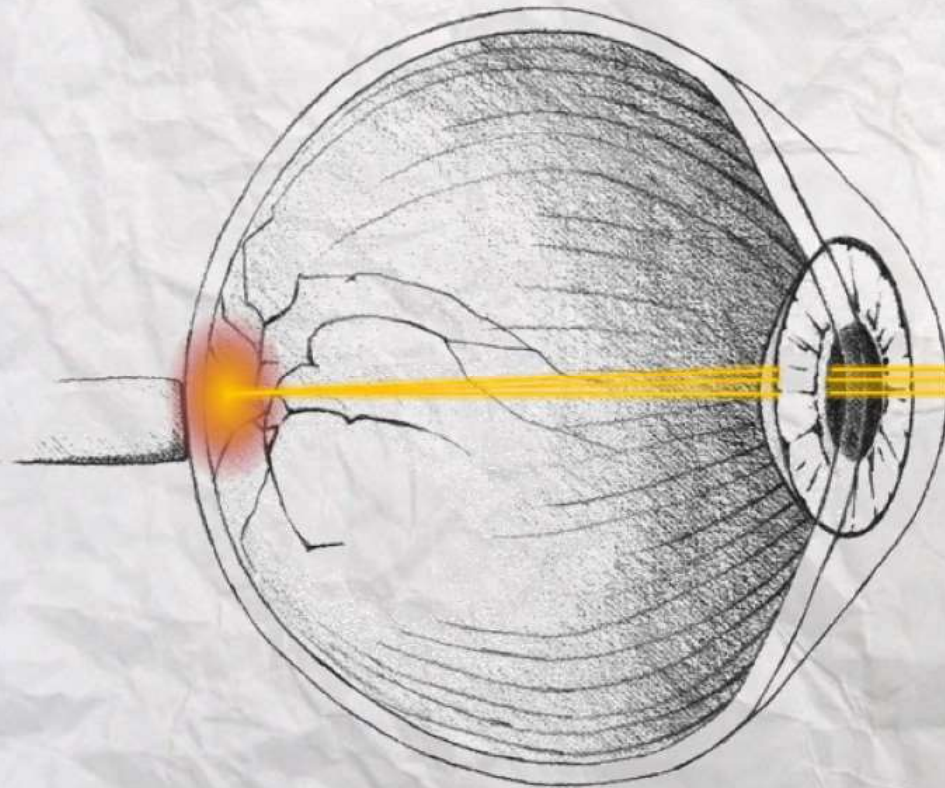


Working principle

BASIC SCHEME OF AN ABERROMETER



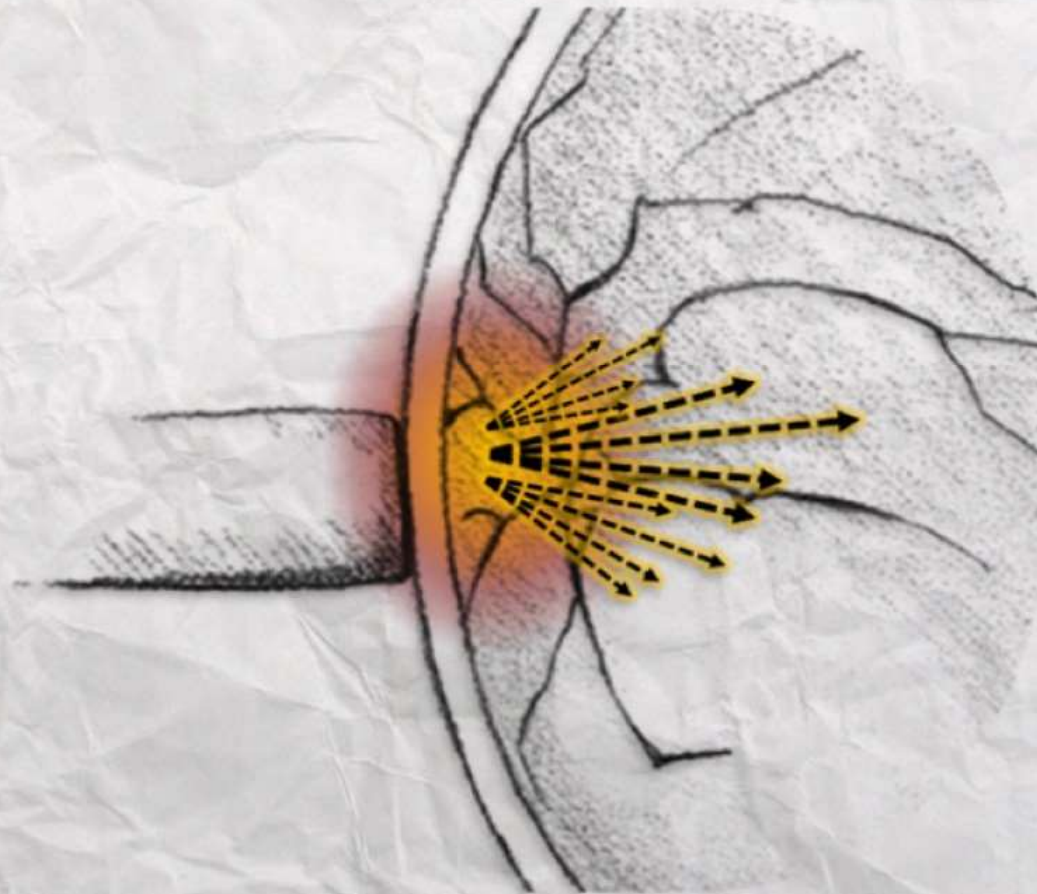
LIGHTING SYSTEM



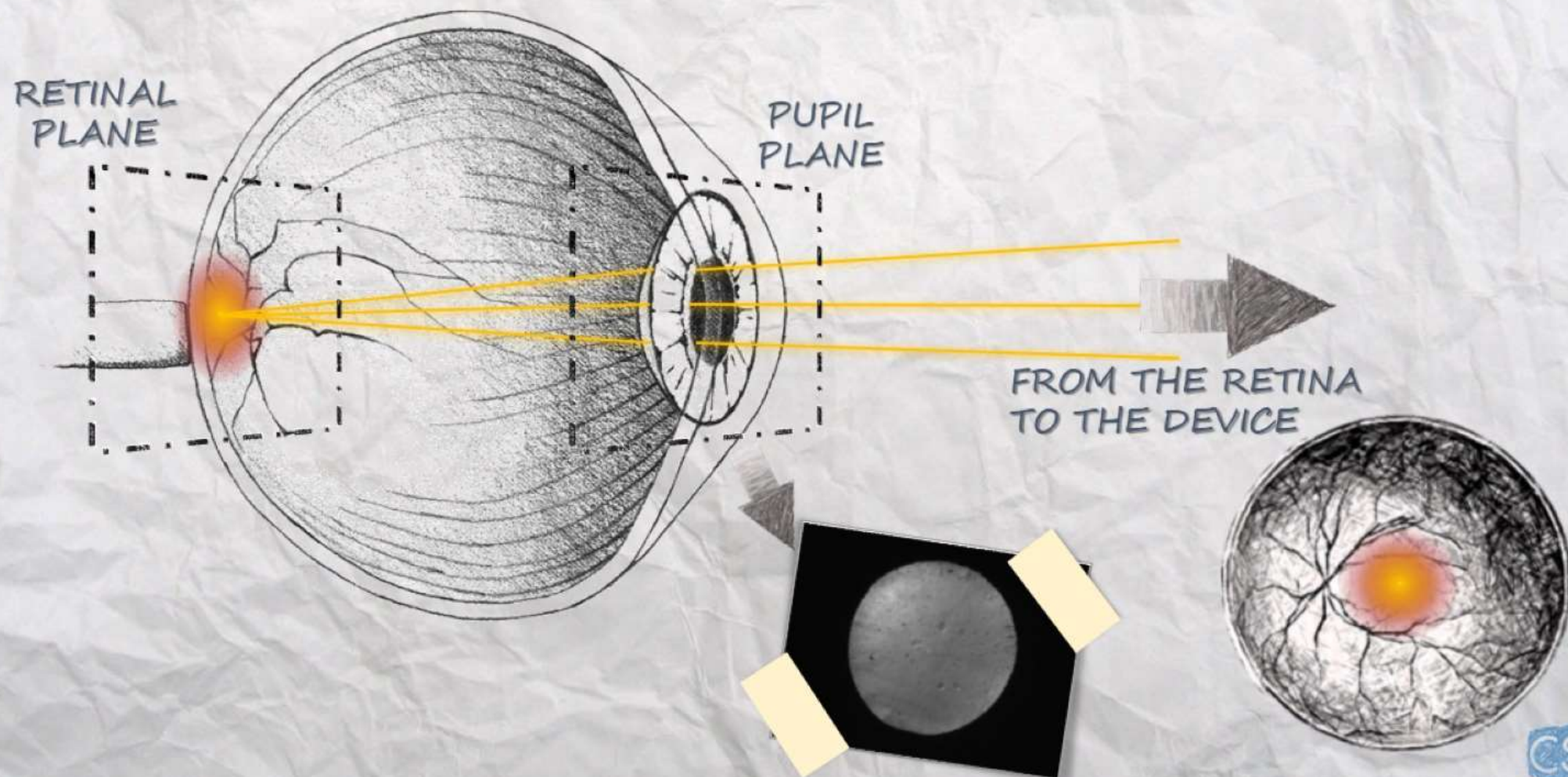
FROM THE DEVICE
TO THE RETINA



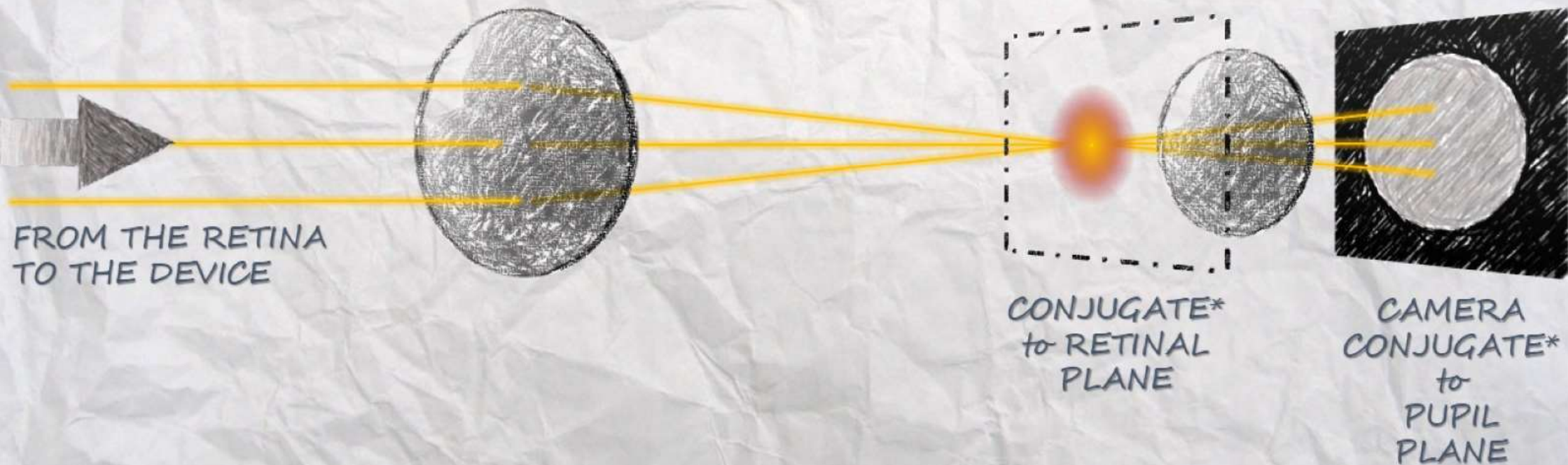
SCATTERING BACK TO THE DEVICE



REFLECTION BACK TO THE DEVICE

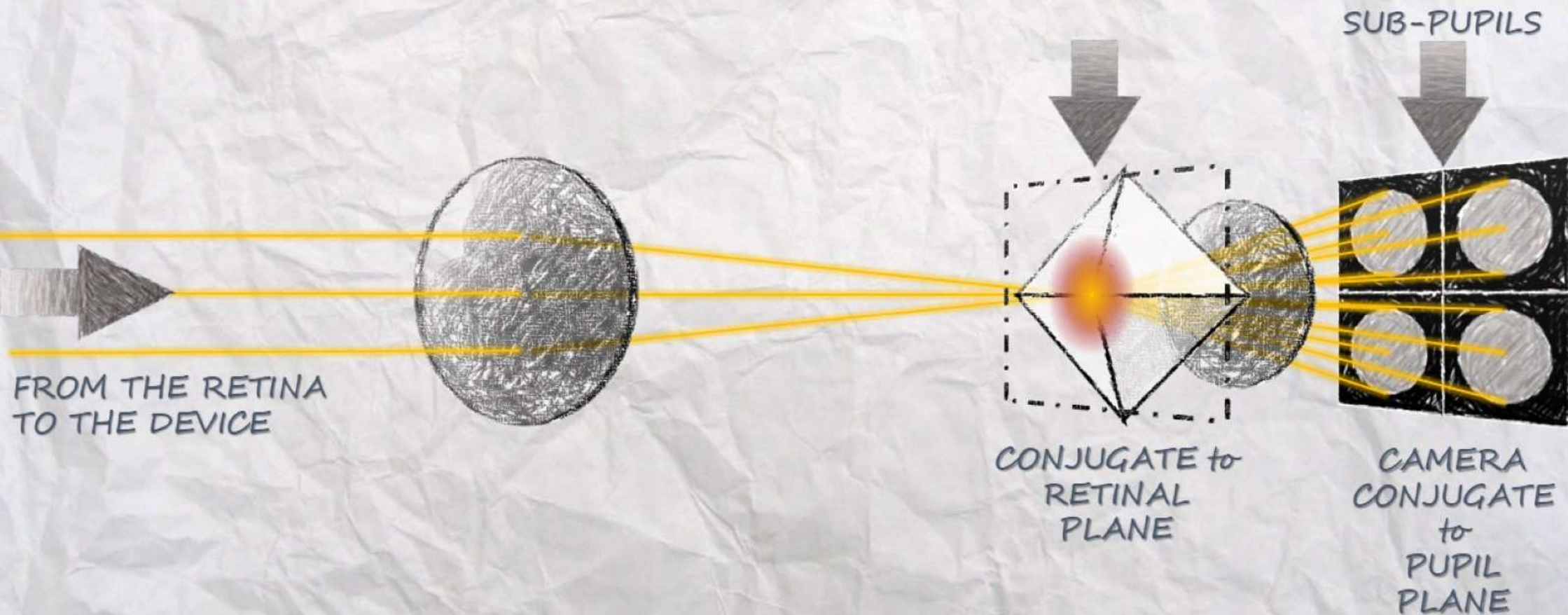


INTO OSIRIS-T...



IN OPTICS, A CONJUGATE FOCAL PLANE OF A GIVEN PLANE P , IS THE PLANE P^ SUCH THAT POINTS ON P ARE IMAGED ON P^* .

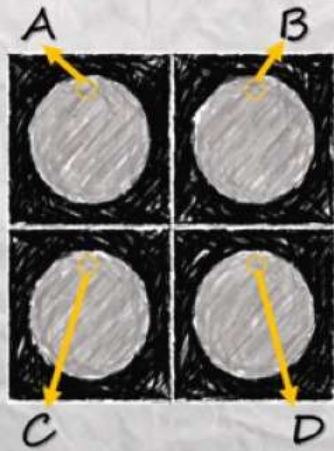
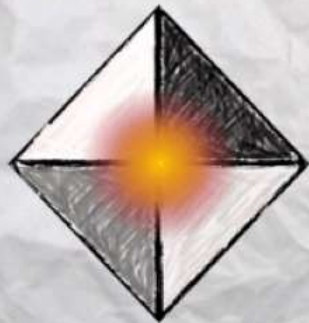
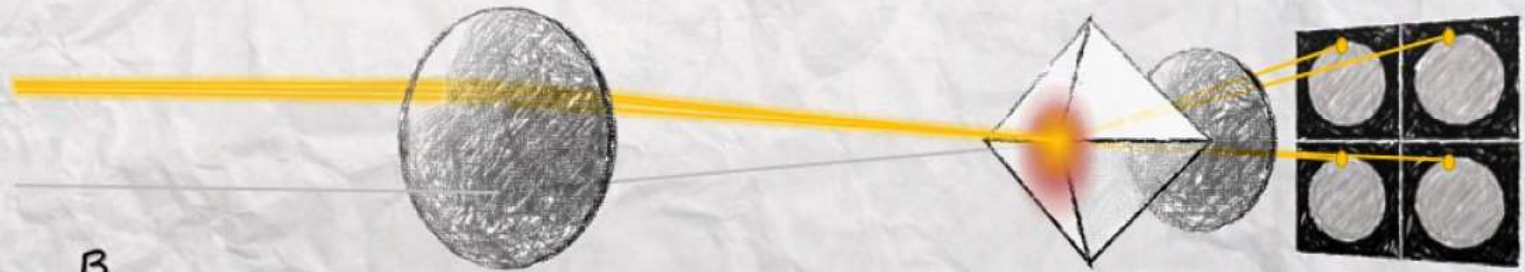
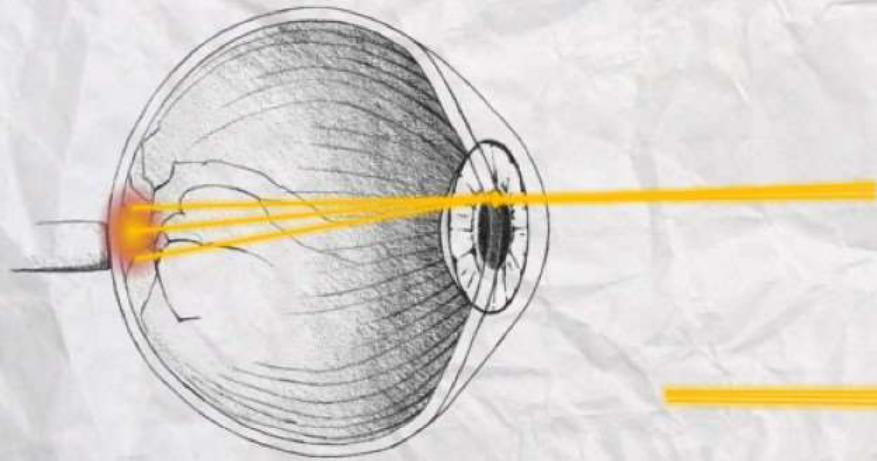
INTO OSIRIS-T...



1996-Roberto Ragazzoni

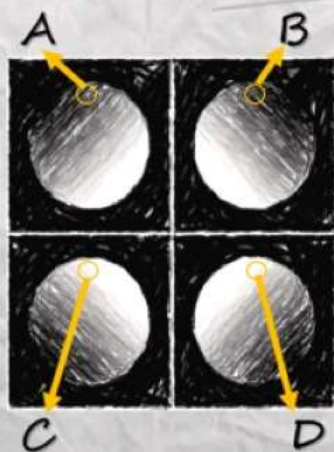
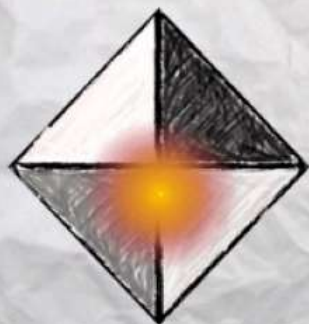
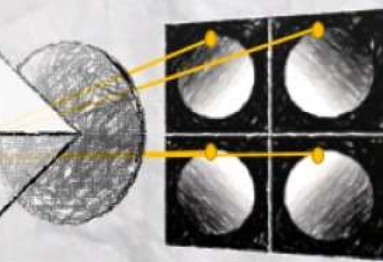
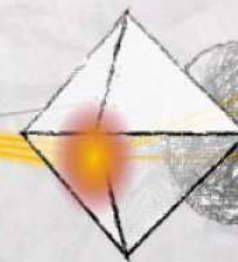
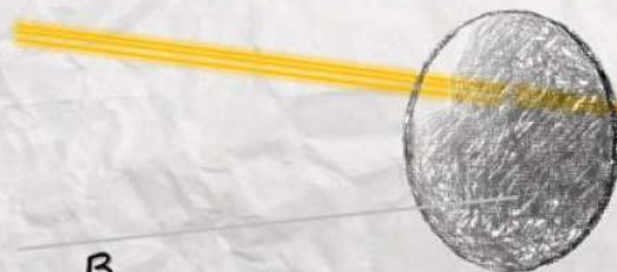
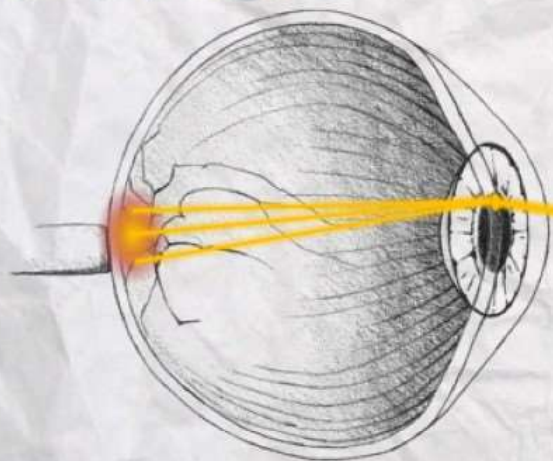


EMMETROPIC RAY (SLOPE = 0): Y-AXIS



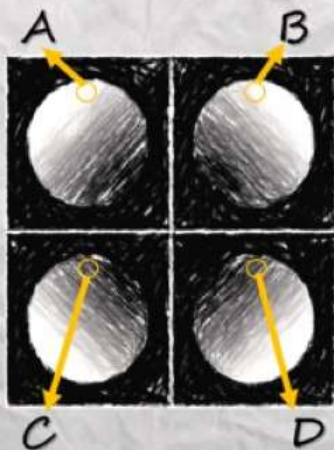
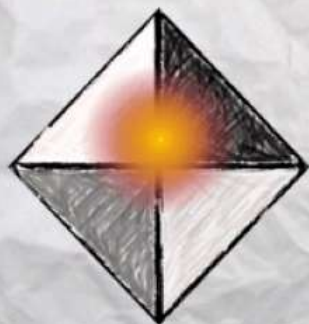
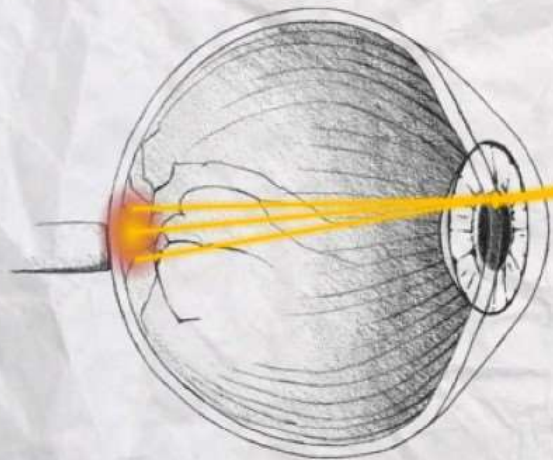
$$A = B = C = D$$

CONVERGENT RAY (SLOPE < 0): Y-AXIS



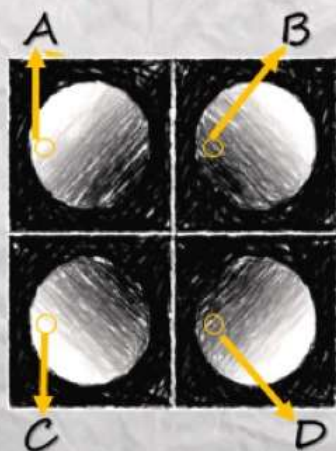
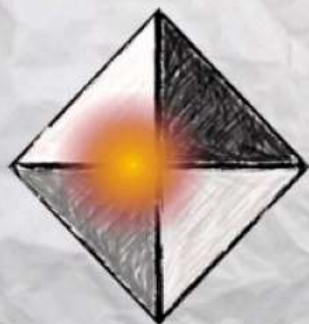
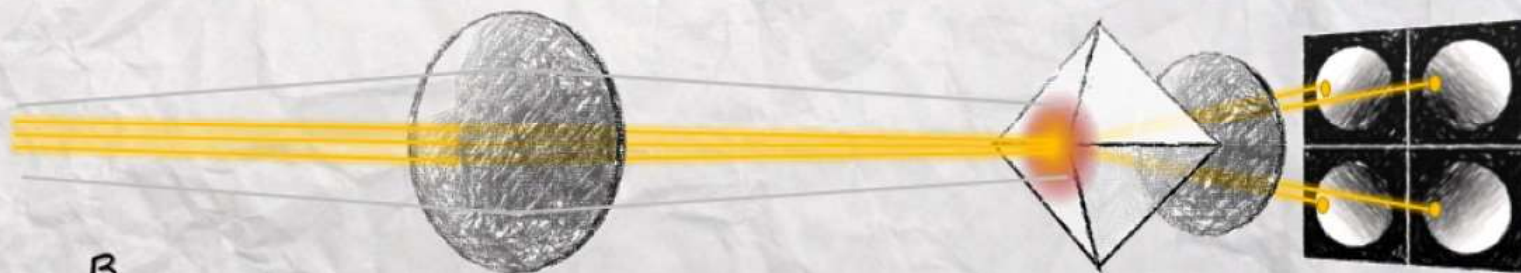
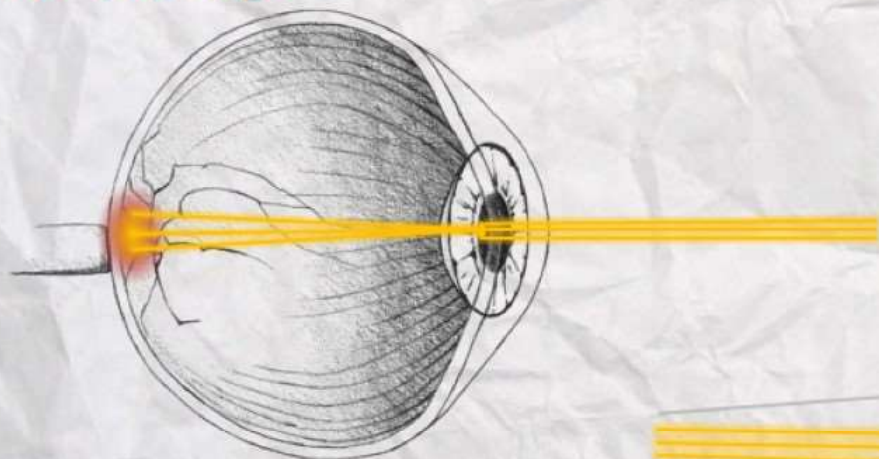
$$\begin{aligned} A &< C \\ B &< D \\ (A=B, C=D) \end{aligned}$$

DIVERGENT RAY (SLOPE > 0): Y-AXIS



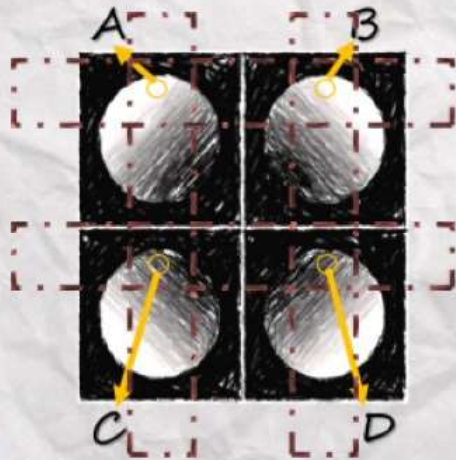
$$\begin{aligned} A &> C \\ B &> D \\ (A=B, C=D) \end{aligned}$$

DIVERGENT RAY (SLOPE > 0): X-AXIS



$$\begin{aligned} A &> B \\ C &> D \\ (A=C, B=D) \end{aligned}$$

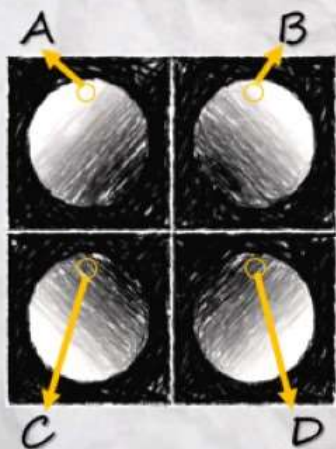
RELATIONSHIP SLOPE-LIGHT INTENSITY



$$\frac{\partial WF}{\partial y} \propto \frac{A+B-C-D}{A+B+C+D}$$

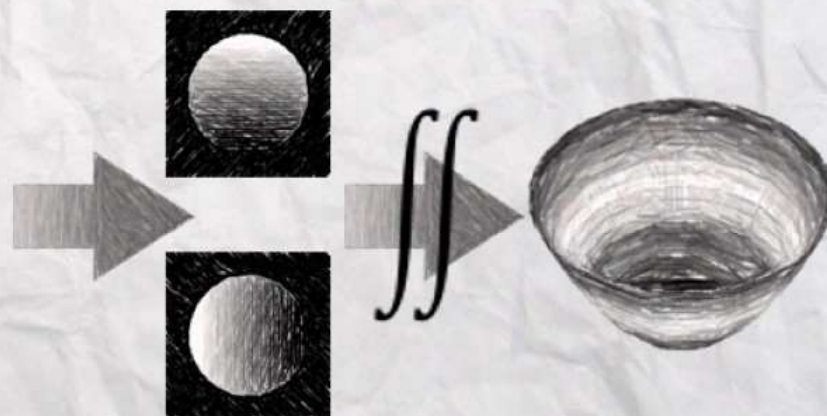
$$\frac{\partial WF}{\partial x} \propto \frac{A+C-B-D}{A+B+C+D}$$

WAVE-FRONT ERROR



$$\frac{\partial WF}{\partial y} \propto \frac{A+B-C-D}{A+B+C+D}$$

$$\frac{\partial WF}{\partial x} \propto \frac{A+C-B-D}{A+B+C+D}$$



REFRACTIVE ERROR (VERGENCE ERROR)

Ocular aberrations with wavefront vergence maps Nam, Thibos and Iskander

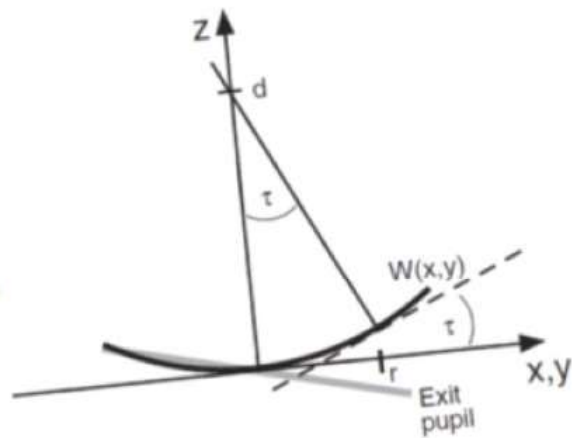
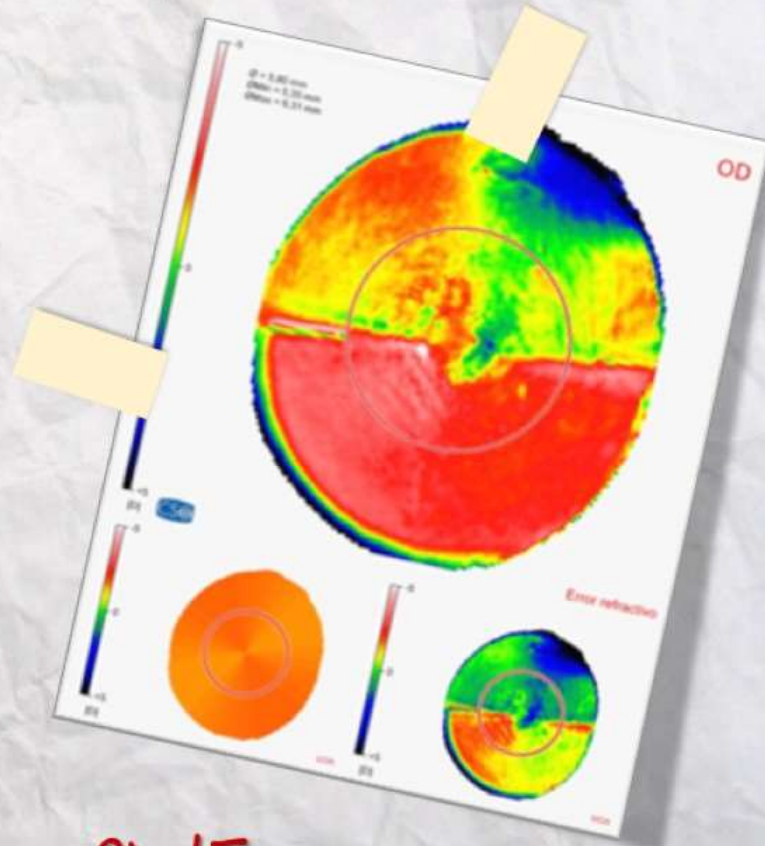


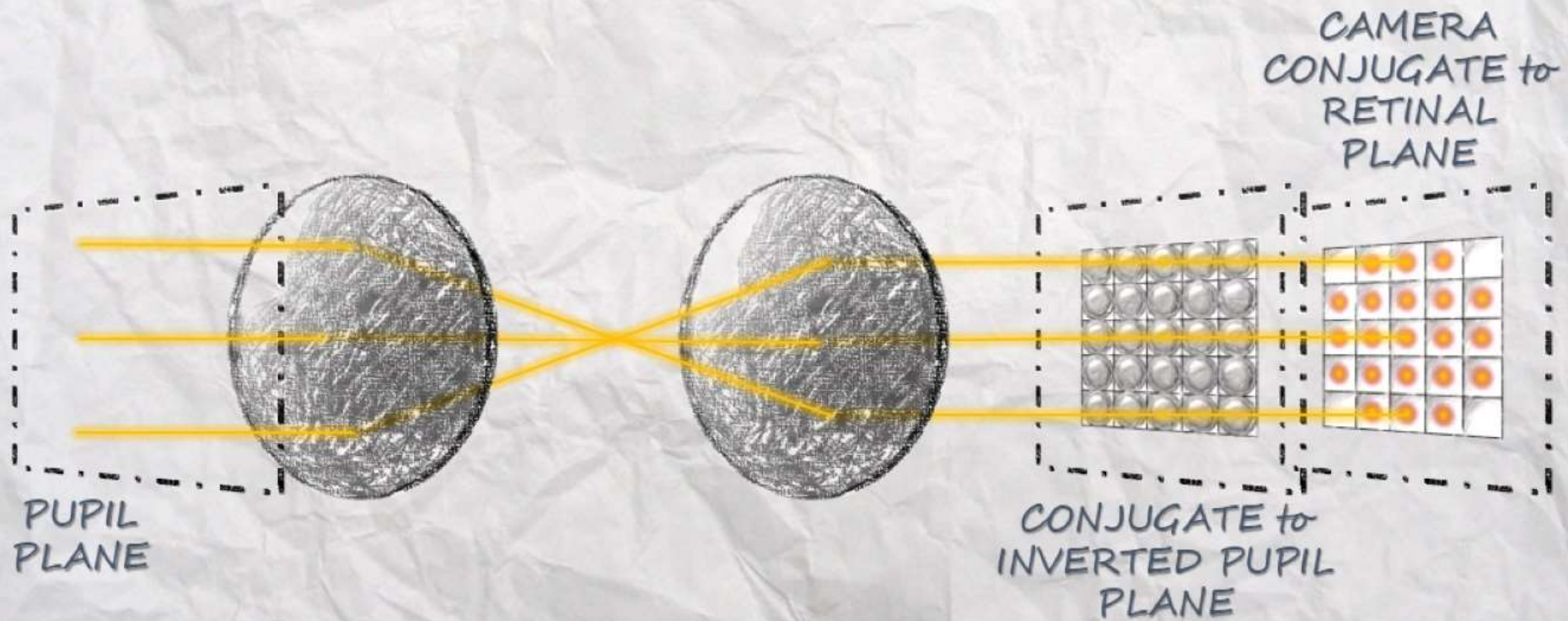
Figure 1. Geometry of the wavefront vergence definition. The z axis indicates the direction of the chief ray, which is not necessarily perpendicular to the exit pupil.

$$V(\rho, \theta) = \frac{1}{\rho} \frac{\partial WF}{\partial \rho} = \frac{1}{\rho} \left(\frac{\partial WF}{\partial x} \cos(\theta) + \frac{\partial WF}{\partial y} \sin(\theta) \right)$$

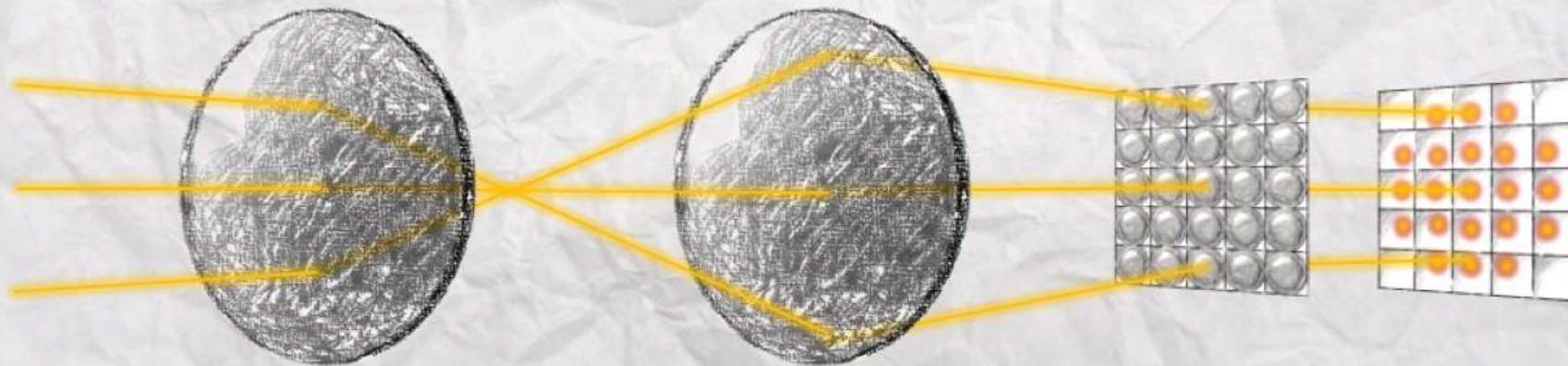


Comparison to HARTMANN-SHACK

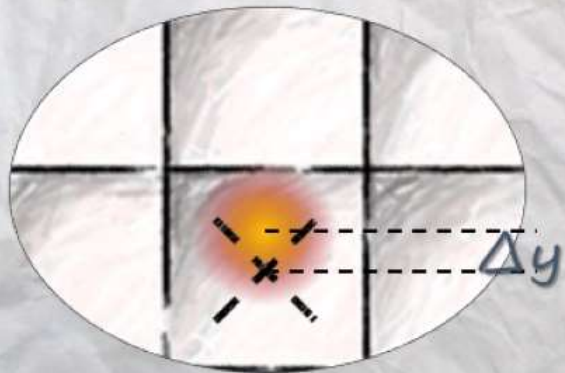
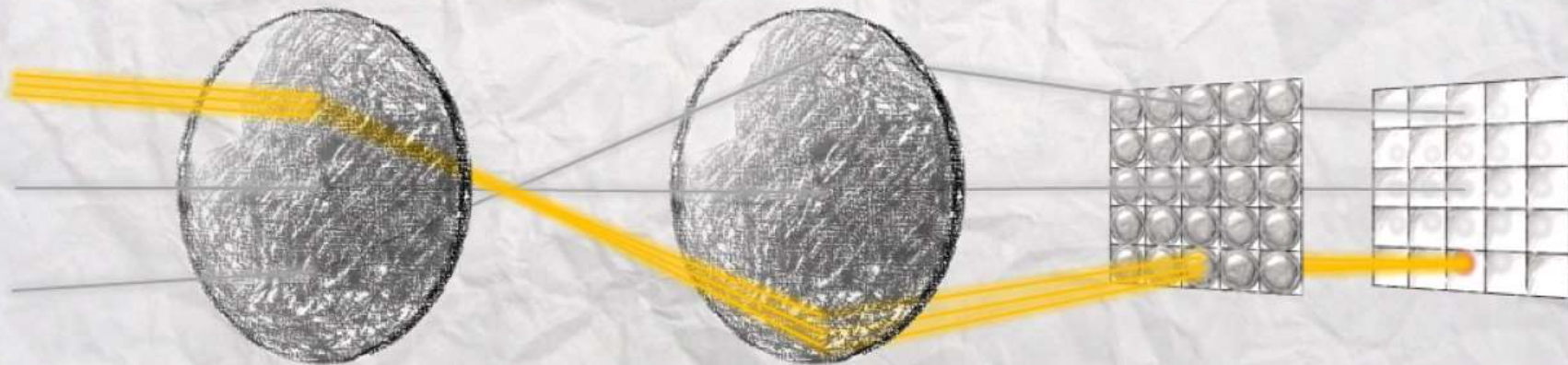
HARTMANN-SHACK



HARTMANN-SHACK: CONVERGENT WF



HARTMANN-SHACK: CONVERGENT RAY

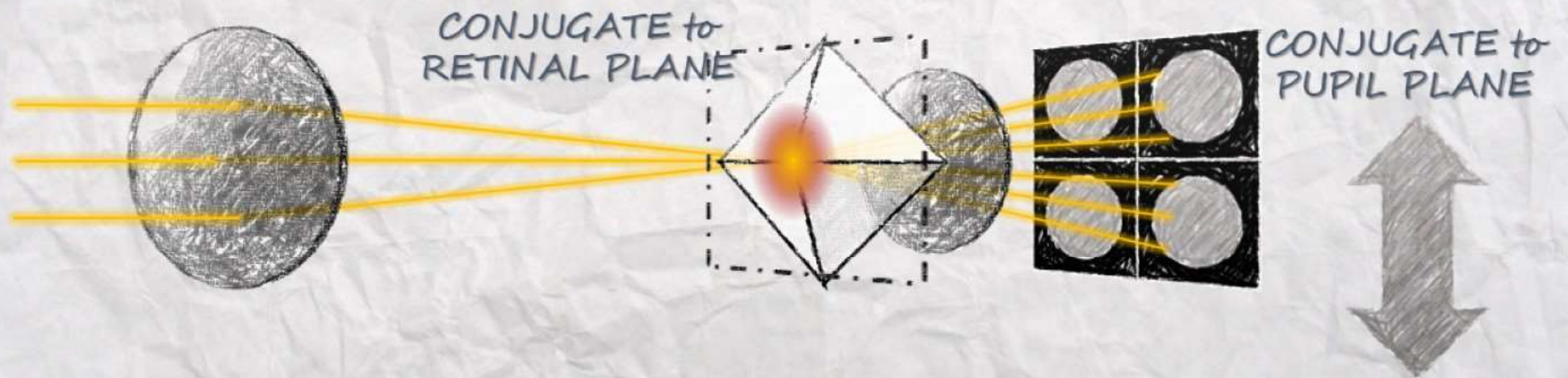


$$\frac{\partial WF}{\partial x} \propto \Delta x$$

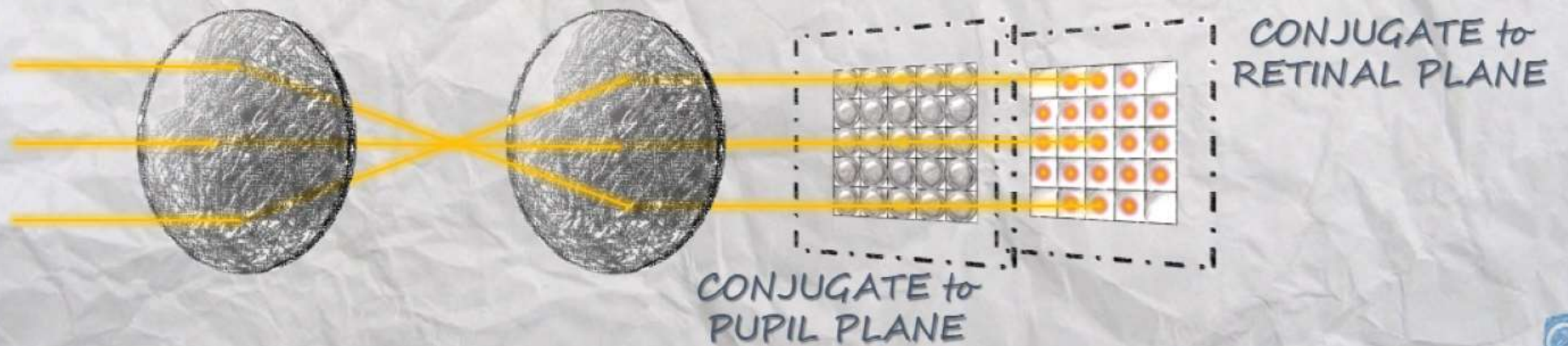
$$\frac{\partial WF}{\partial y} \propto \Delta y$$

COMPARISON: OPTICAL SETUP

PWS

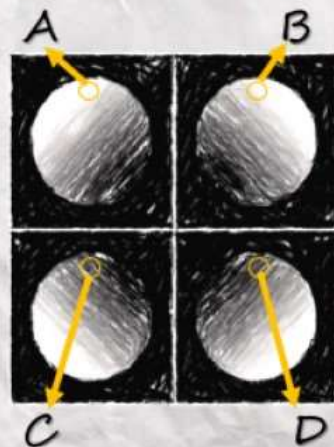


HS



COMPARISON: WORKING PRINCIPLE

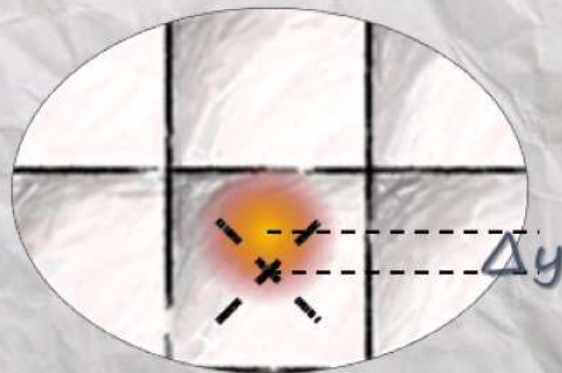
PWS



$$\frac{\partial WF}{\partial x} \propto \frac{A+C-B-D}{A+B+C+D}$$

$$\frac{\partial WF}{\partial y} \propto \frac{A+B-C-D}{A+B+C+D}$$

HS



$$\frac{\partial WF}{\partial x} \propto \Delta x$$

$$\frac{\partial WF}{\partial y} \propto \Delta y$$

COMPARISON: RESOLUTION

N = # POINTS ON A SUB-PUPIL

- 45.000 SAMPLES ($\phi = 9.0 \text{ mm}$)
- SPATIAL RESOLUTION: $41 \mu\text{m}$

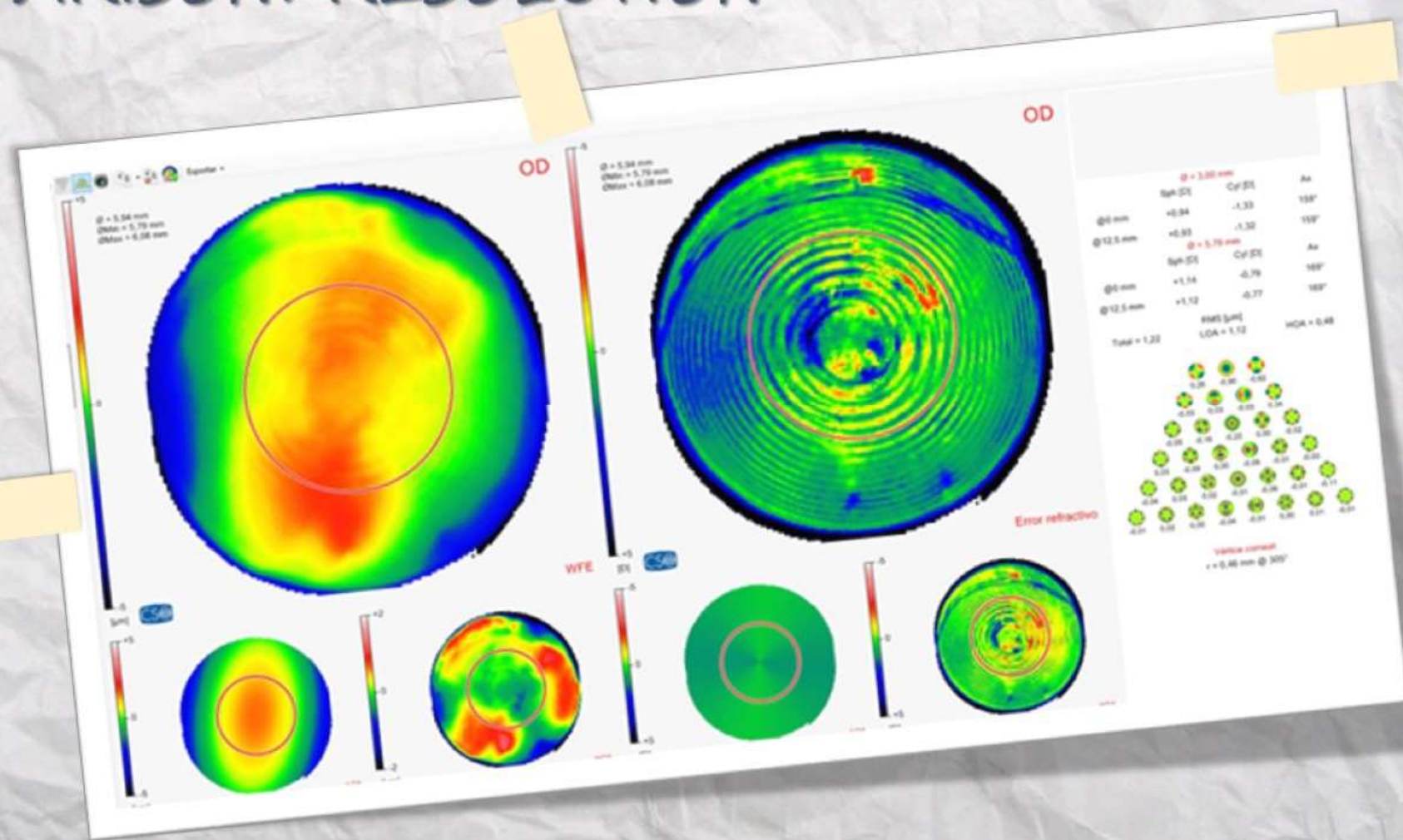
N = # LENSES ON THE LENSLET

- 1.000-2.000 SAMPLES ($\phi = 9.0 \text{ mm}$)
- SPATIAL RESOLUTION: $250-125 \mu\text{m}$

PWS

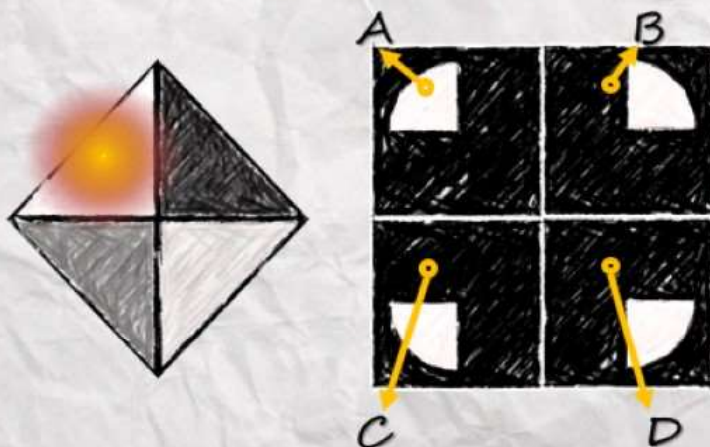
HS

COMPARISON: RESOLUTION



COMPARISON: SATURATION & DINAMIC RANGE

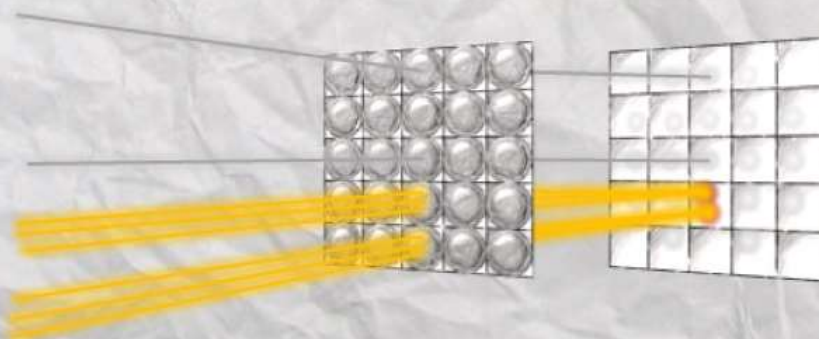
PWS



$$\frac{\partial WF}{\partial y} \propto \frac{A+B-C-D}{A+B+C+D} = 1$$

$B=C=D=0$

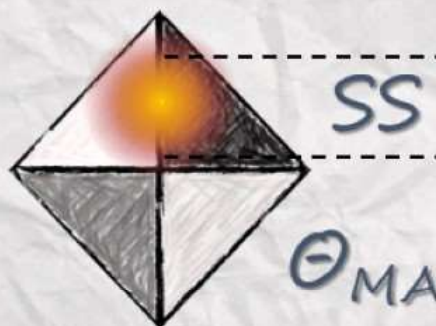
HS



$$\frac{\partial WF}{\partial y} \propto \Delta y = ?$$

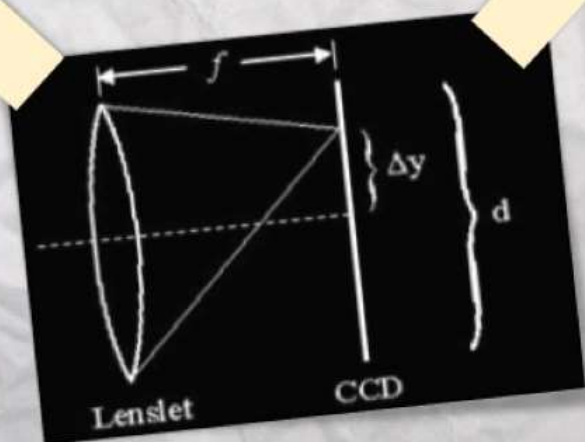
COMPARISON: SATURATION & DYNAMIC RANGE

PWS

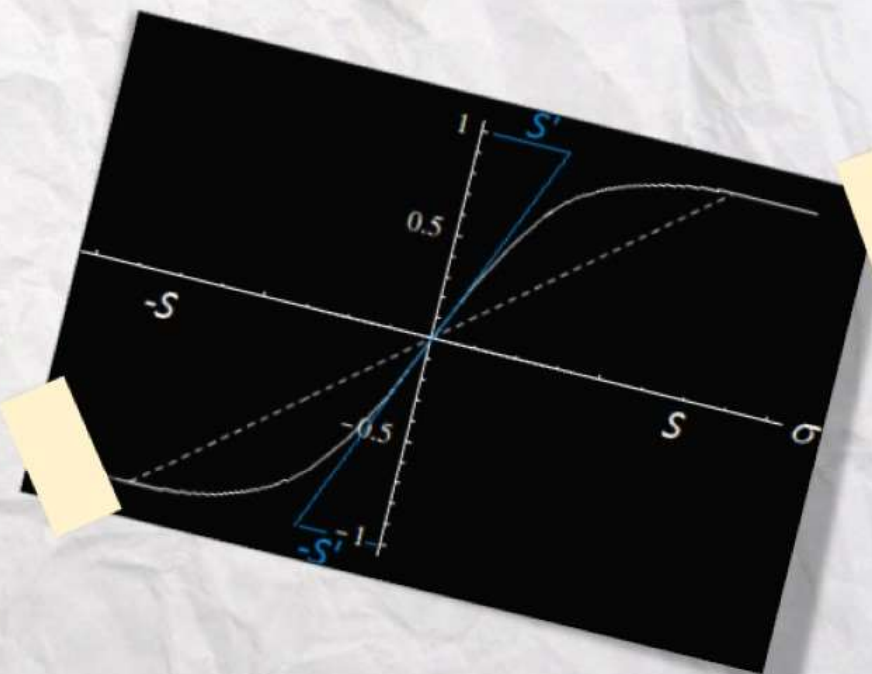


$$\Theta_{MAX} \propto SS$$

HS



$$\Theta_{MAX} \propto \Delta y / f = d / 2f$$



COMPARISON: PROCESSING

DIRECT INTEGRATION METHOD

- 30 Fps (REAL TIME WF IMAGING)
- FITTING «OPTIONAL»

MODAL (ZERNIKE FITTING)

- WF IMAGING «OFF LINE»
- FITTING MANDATORY

HS PWS

PROCESSING (REAL TIME ACCOMMODATION MEASUREMENT)

